## ESCJ 16c: <br> Java to Guarded Commands translation

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Some additional comments from Cormac in italics.
Compaq Confidential.
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To do:

- Write static body VC gen.
- Define meta functions in a sensible order.
- Loop invariants (and/or "-Fast" translation of loops).
- The logic should assume labels to be distinct.
- Rename the guarded command block L: S end to something that doesn't say "block" to avoid confusion with the Java block statement.
- Reconcile our AST with Raymie's and Cormac's.
- Pass over document for consistency (for example, make $L S$ not be a keyword).
- Choose "freshly generated variable names" to produce meaningful counterexample contexts.
- Note that ESC/Java currently does not provide a way to monitor the contents of an array.
- Write down what we assume about null about fields of null. For example, allocTime(null) < pre\$alloc and $f[$ null $]!=$ null for non_null fields $f$. (Hm, note that our assumptions are not consistent in the initial state if two inconsistent invariants are declared (like $x=0$ and $x==2$ ), or if an invariant $f==$ null is declared for a non_null field f.)
- State, in the ESC/Java Annotation Reference Manual, that the formal parameters of a method override are not allowed to mention the non_null modifier (instead, it implicitly inherits any non_null modifier of the corresponding formal parameter of the method being overridden). Also, state that the free variables of a requires clause of a method must be as visible as the method itself. Also say that an ensures clause of a constructor is allowed to mention RES. Also, state that a private field is allowed to be mentioned in a postcondition only if the method is final or private or if the enclosing class is finalotherwise, a syntactic warning is produced.
- Give location information for each check command.
- Introduce Java+ grammar for routine declarations, and use where appropriate.
- Reconcile error names with ESCJ 17.
- Update ESCJ 17 to use max instead of min for lock sets.
- Make index of meta functions.


## 0 Introduction

This note describes a translation of annotated Java into a guarded command-like language for the purpose of generating verification conditions. This note is not about resolution of names in Java, so we assume where convenient that names have been unique-ified. In particular, we assume the names of types, fields, and methods have been unique-ified. In the case of methods, unique-ification takes care of overloading by taking into account the types of formals.

We assume that we are given an AST (as described in section 1) for a Java method (or other body of code) to be checked, where all names (local variables, parameters, fields, methods, types) have already been resolved. Our goal is to produce a guarded command gc (as described in section 2) such that, with the background predicate (call it BG) produced according to ESCJ 8, The logic of ESC/Java, the condition

$$
\mathrm{BG}==>\text { wlp.gc.(true, true, false })
$$

is valid if and only if $m$ meets its specification. That is, the condition

## BG \&\&!wlp.gc.(true, true, false)

is satisfiable if and only if m does not meet its specification. It behooves us now to explain $w l p$ and "meets its specification".

For any guarded command gc and predicates $\mathrm{N}, \mathrm{X}$, and W , the predicate wlp.gc. $(\mathrm{N}, \mathrm{X}, \mathrm{W})$ holds in exactly those initial states from which execution of gc either terminates normally in (a state satisfying) $N$, terminates exceptionally in X , goes wrong in W , or doesn't terminate at all. The computation of (an approximation to) $w l p$ is described in section 2 .

When we say that a Java method meets its specification, we have a particular notion in mind. This notion turns out to be unsound, because there are several kinds of errors that we don't check for. For one thing, we do not consider integer overflows or infinite loops to be violations of a method's specification. Also, we know that our treatment of modifies clauses is unsound, a choice we made in hope of making the ESC/Java tool easier to use without significantly undermining its ability to find errors. Furthermore, user-supplied annotations can introduce unsoundness, in both obvious ways--for example, by suppressing certain checks or introducing bogus assumptions--and in non-obvious ways--for example, by giving a lock order that is not a partial order.

[^0]
## 1 Java-like AST

We use italics for non-terminals and bold face for keywords. Sometimes we prefix a non-terminal with a descriptive comment (word) ending in an underscore. An asterisk denotes any number of occurrences of the immediately preceding terminal, non-terminal, or parenthesized construction.

We take the following non-terminals as primitives: Identifier, Literal, UnaryOp, BinOp.

```
Stmt::=
    block Stmt* end
| var Modifier* Identifier [= Expr]
    Note that the Expr might be an array initializer expression. The Identifier introduced goes out of scope at the end of the
    innermost enclosing block, for, or switch statement, or method body.
| label Identifier Stmt
        The label is implicit in the address of the AST node. (Cormac's annotations are in this font).
    | skip
| eval Expr
    Note that assignments are expressions, so the front end translates assignment statements into eval statements. Similarly, all
        method invocation statements are translated into eval statements. Note that the type of Expr is void if Expr is an invocation of a
        void method.
| if (Expr) Stmt else Stmt
    We assume that omitted else clauses have been replaced by else skip.
| Identifier: while (Expr) { loop_invariant SpecExpr* } Stmt
    We assume that every while, do, and for statement has an explicit label, possibly provided by the front end.
    This label is implicit in the address of the AST node. After typechecking, the statement that is being aborted or continued
    BreakStmt and ContinueStmt AST node can be retrieved via the static method FlowInsensitiveChecks.getBranchLabel.
    The LabelStmt AST node is therefore not used by the Java-to-GC translation.
| Identifier: do {loop_invariant Expr* } Stmt while (Expr)
| Identifier: for (Stmt** Expr ; Expr*) {loop_invariant Expr* } Stmt
    The Stmt* is the for initializer. It consists of either one var statement (whose scope is the entire for statement) or a list of
        expressions. The first Expr is the loop guard. The first Expr* is a list of for update expressions. The final Stmt is the loop body.
| break Identifier | continue Identifier
        We assume that every break and continue statement has an explicit label, possibly provided by the front end.
        This label is implicit in the address of the AST node.
    return [Expr]
    throw Expr
    try Stmt catch (Type Identifier Stmt)* end
        Each Type specifies a class of exceptions for which the corresponding Stmt is a handler; the Identifier may be used in the
        corresponding Stmt to denote the exception caught.
| try Stmt finally Stmt
        We assume the front end translates the Java try catch finally statement into a try finally statement whose first component is a
        try catch.
    | Identifier: switch (Expr) (case [Expr] Stmt*)* end
        An omitted Expr means the default case. We assume there is exactly one default case. If the programmer doesn't supply one,
        the translation can add case break Identifier (where the label Identifier is the same as that of the switch statement) as the first or
        last case.
        The translation does not add the default case, if one is not given in the source program.
| synchronized (Expr) Stmt
    The Expr denotes an object treated as a mutex.
| construct Identifier (Expr*)
    This statement is a constructor invocation (see ExplicitConstructorInvocation [JLS, 19.8.5]). It is called ConstructorInvocation
        in the ESC/Java front end.
        We assume that when the Java source for a constructor body for a proper subtype of Object does not begin with an explicit
        constructor invocation, the ESC/Java front end supplies the implicit constructor invocation as defined by [JLS, 8.6.5].
        The Identifier (which the type checker will already have disambiguated using the static types of this and of the Expr*) names the
        superclass or sibling constructor to be called. The Expr* are the arguments to that constructor.
        The Identifier is given via the decl field of the MethodInvocation AST node.
| assert SpecExpr | assume SpecExpr
    These statements come from ESC/Java annotations rather than from Java proper.
| unreachable
Expr ::=
    this
| Literal
```


## | Designator

## UnaryOp Expr

Expr BinOp Expr
| Expr CondBinOp Expr
A CondBinOp is one of conditional binary operators $\|$ and \&\&.
| (Expr? Expr: Expr)
| newarray Type Expr*
The Type specifies the element type of the array to be allocated. The Expr* specifies the dimensions of the array to be allocated.
| array Type Expr*
The Type specifies the element type of the array to be allocated and initialized. The Expr* specifies the initial values of the elements, and the number of Expr* indicates the length of the array to be allocated.
| Expr instanceof Type
The Type must be an object type.
| (Type) Expr
The Type is the type to which the Expr is to be cast.
| Designator $=$ Expr
The language requires that the static type of the Expr be assignment covertible to the static type of the Designator. When assignment conversion may change the value of the right-hand side, for example when widening a long to a float, we assume that the ESC/Java front end supplies an explicit cast.
The front end does not supply the explicit case. We may want to add a brief intermediate pass that would do this.
| Designator BinOp = Expr
| Designator BinOp
The Java expression $\mathrm{D}++$ falls into the Designator BinOp category, where the BinOp is + (which + it is depends on the type of D). The Java expression ++D is preprocessed into $\mathrm{D}+=1$, and hence falls into the Designator BinOp $=$ Expr category. What happened with these expressions in Cormac and Raymie's AST?
The pre- and post- increment and decrement operators are translated into UnaryExpr nodes, where the tag is INC or DEC for the pre- operators, and POSTFIXINC or POSTFIXDEC for the post- operators.
| MethodInvocation

Why does Cormac and Raymie's AST contain a ParenExpr class? And what about the AmbiguousVariableAccess? Can we assume that these have been translated away by the front end by the time we get control?
The ParenExpr class preserves information about where parens occurred in the source program. This information is useful for pretty-printing. The AmbiguousVariableAccess is removed by the name resolution pass, as is the
AmbiguousMethodInvocation AST node.
Designator ::=
Identifier
The Identifier denotes a local variable, parameter, or global variable.
Cormac and Raymie's AST has a class called LocalVariableAccess. Does that include parameters and globals?
The LocalVariableAccess AST includes parameters and globals.
| Expr. Identifier
The Identifier denotes a field.
| Expr[Expr]
There are four kinds of method invocations. In each case, we assume that the Identifier has been fully disambiguated.

## MethodInvocation ::=

In all of these cases, the Identifier is given via the decl field of the MethodInvocation AST node.
new Type Identifier (Expr*)
The Type specifies the class of the object to be allocated. The Identifier (which the type checker will already have disambiguated using the Type and the types of the Expr*) names the constructor. The Expr* are the arguments to the constructor.
| Identifier (Expr*)
The Identifier names a static method. (The AST actually represents this form of method invocation as Type.Identifier(Expr*), but this document can ignore the Type, because we assume that the Identifier has been fully disambiguated.)
| Expr. Identifier (Expr*)
In this case, the Identifier may be either an instance method or a static method. If the Identifier names an instance method, then the result of evaluating the first Expr will be supplied as the actual self parameter to the method call. If the Identifier names a static method, then the Expr will be evaluated for side effects and the result discarded. In either case, the static type of the Expr will already have been used by the type checker to disambiguate the Identifier.
| super . Identifier (Expr*)
In this case, too, the Identifier may be either an instance method or a static method. If the Identifier names an instance method, then this will be supplied as the actual self parameter to the method call. If the Identifier names a static method, then the keyword super is ignored by the translation. In either case, the direct superclass of the static type of this will already have been used by the type checker to disambiguate the Identifier.

```
SpecExpr ::=
    Expr
        This Expr must be side-effect free.
        Actually, this is really supposed to be an Expr in which any subexpression may be a SpecExpr.
| (forall (Type Identifier)* SpecExpr)
| (exists (Type Identifier)* SpecExpr)
((Iblpos Label SpecExpr)
| (lbIneg Label SpecExpr)
PRE(SpecExpr)
| fresh(SpecExpr)
```

Type ::=
boolean | byte | char | double | float | int | long | short
| Identifier
The Identifier is a declared class or interface, possibly a pre-declared name like Object.
| Type[]

## 2 Guarded command AST

Our translation targets a guarded command language whose syntax is given below.
We take the following non-terminals as primitives: Identifier, Literal, UnaryOp, BinOp, Function. The first four of these are supersets of the corresponding non-terminals in the Java AST. The guarded command non-terminal variable includes every Java variable, field, and label, as well as some variables introduced by the translation. The non-terminal Function includes the functions described in the Logic of ESC/Java. boy, this paragraph needs fixin'.

```
command ::=
    lhs=rhs
skip
raise
assert rhs
assume rhs
var variable* in command end
command; command
command ! command
command [] command
loop { inv condition* } command end
call MethodName (rhs*)
lhs ::=
    variable
| variable[rhs]
| variable[rhs][rhs]
rhs ::=
    lhs
| Literal
| UnaryOp rhs
| rhs BinOp rhs
| Function (arg_rhs*)
(forall variable}\mp@subsup{}{}{+}:: rhs
| (exists variable}\mp@subsup{}{}{+}:: rhs
| (lblneg Identifier rhs)
| (lblpos Identifier rhs)
condition ::=
    errorName,location : rhs
```

In the last line, errorName is the name Free or an error name as described ESCJ 17, ESC/Java Annotation Reference Manual, and location is Java source code location. If errorName is Free, the location field is not used and can be set to the null location.

In many cases in this document, we have omitted the location of a condition triple. In those cases, the implicit location refers to a location near where the Java+ expression that is translated into the $r h s$ is found. This document should probably make a precise choice of location explicit.

We define three deconstructor functions on conditions:

```
ErrorName[[ EN, L : e ]] == EN
Location \([[\) EN, L: e ]] == L
Predicate \([[\) EN, L : e ]] \(==\mathrm{e}\)
```

In addition, we define the following shorthands:

```
if e then S0 else S1 end == (assume e; S0 [] assume ! e ; S1)
block L:S end == (S ! if ec == L then skip else raise end)
raise L == (EC=L; raise)
fail == assumefalse
modify lhs == var }x\mathrm{ in lhs = x end
```

where e is a $r h s, \mathrm{~S}, \mathrm{~S} 0, \mathrm{~S} 1$ are command, L is a label, and ec is a special variable introduced by the translation.

We also define a shorthand check whose grammar is:

## check location, condition

and whose definition is:

```
check LUse, EN, LDecl : e ==
    \#if (EN is Free)
    skip
    \#elsif (checking of EN is enabled at LUse and at LDecl)
    assert (Iblneg MakeLabel[[ EN, LDecl, LUse ]] e)
    \#else
    assume e
    \#end
```

where MakeLabel somehow concatenates its arguments into an identifier.
In many cases in this document, we have omitted LUse. In those cases, the implicit location refers to a location near where the Java+ expression or statement that is translated into the check is found. This document should probably make a precise choice of location explicit.

### 2.0 Semantics of guarded commands

The commands are defined in terms of predicate transformers. For any command $S$ and predicates $N$ and $X$ on the post-state of S , we define $e j p[[\mathrm{~S}, \mathrm{~N}, \mathrm{X}]]$ as a weak precondition sufficient to guarantee that any normally terminating execution of $S$ establishes $N$, that any exceptionally terminating execution of $S$ establishes $X$, and that no execution of $S$ goes wrong. In particular, we have

$$
e j p[[\mathrm{~S}, \mathrm{~N}, \mathrm{X}]]==>\text { wlp.S.(N, X, false) }
$$

For any $\mathrm{N}, \mathrm{X}$, and W , we have:

```
wlp.(v=e).(N, X,W)== N[ l e e ]
wlp.(v[e0] = e).(N, X, W) == N[ v store(v, e0, e) ]
wlp. (v[e0][e1] = e). (N, X,W) == N[v store(v, e0, store(select (v, e0), e1, e) ]
```

```
wlp.skip. \((\mathrm{N}, \mathrm{X}, \mathrm{W})==\mathrm{N}\)
wlp.raise. \((\mathrm{N}, \mathrm{X}, \mathrm{W})=\mathrm{X}\)
wlp. \((\operatorname{assert} \mathrm{e}) .(\mathrm{N}, \mathrm{X}, \mathrm{W})==(\mathrm{e} \& \& \mathrm{~N}) \|(!\mathrm{e} \& \& \mathrm{~W})\)
wlp. \((\) assume e\() .(\mathrm{N}, \mathrm{X}, \mathrm{W})==(\mathrm{e}==>\mathrm{N})\)
\(w l p .(\operatorname{var} \mathrm{v} 1 \ldots \mathrm{vn}\) in S end).( \(\mathrm{N}, \mathrm{X}, \mathrm{W})==(\mathrm{ALL} \mathrm{v} 1 \ldots \mathrm{vn}:: ~ w l p . \mathrm{S}) .(\mathrm{N}, \mathrm{X}, \mathrm{W}))\)
                                    (* provided \(\mathrm{v} 1 \ldots\) vn are free in \(\mathrm{N}, \mathrm{X}\), and W *)
wlp.(S0; S1, ).(N, X, W) \(==\) wlp.S0.(wlp.(S1).(N, X, W), X, W)
wlp.(S0! S1, ).(N, X, W) == wlp.S0.(N, wlp.S1.(N, X, W), W)
wlp.(S0 [] S1).(N, X, W) \(==\) wlp.S0.(N, X, W) \&\& \(w l p . S 1 .(N, X, W)\)
```

For any N and X , we define:

```
\(e j p[[\mathrm{v}=\mathrm{e}, \mathrm{N}, \mathrm{X}]]=\mathrm{N}\left[\begin{array}{ll}\mathrm{V} & \mathrm{e}\end{array}\right]\)
\(e j p[[\mathrm{v}[\mathrm{e} 0]=\mathrm{e}, \mathrm{N}, \mathrm{X}]]==\mathrm{N}[\mathrm{v} \quad \operatorname{store}(\mathrm{v}, \mathrm{e} 0, \mathrm{e})]\)
\(e j p[[\mathrm{v}[\mathrm{e} 0][\mathrm{e} 1]=\mathrm{e}, \mathrm{N}, \mathrm{X}]]==\mathrm{N}[\mathrm{v} \quad \operatorname{store}(\mathrm{v}, \mathrm{e} 0, \operatorname{store}(\operatorname{select}(\mathrm{v}, \mathrm{e} 0), \mathrm{e} 1, \mathrm{e})]\)
\(e j p[[\) skip, \(\mathrm{N}, \mathrm{X}]]==\mathrm{N}\)
\(\operatorname{ejp}[[\) raise, \(\mathrm{N}, \mathrm{X}]]==\mathrm{X}\)
\(e j p[[\operatorname{assert} \mathrm{e}, \mathrm{N}, \mathrm{X}]]==\mathrm{e} \& \& \mathrm{~N}\)
\(e j p[[\) assume \(\mathrm{e}, \mathrm{N}, \mathrm{X}]]==(\mathrm{e}==>\mathrm{N})\)
\(e j p[[\operatorname{var} \mathrm{v} 1 \ldots \mathrm{vn}\) in S end, \(\mathrm{N}, \mathrm{X}]]==(\operatorname{ALL} \mathrm{v} 1 \ldots \mathrm{vn}:: e j p[[\mathrm{~S}, \mathrm{~N}, \mathrm{X}]])\)
                            (* provided \(\mathrm{v} 1 \ldots \mathrm{vn}\) are free in N and \(\mathrm{X} *\) )
\(e j p[[\mathrm{~S} 0 ; \mathrm{S} 1, \mathrm{~N}, \mathrm{X}]]==e j p[[\mathrm{~S} 0, e j p[[\mathrm{~S} 1, \mathrm{~N}, \mathrm{X}]], \mathrm{X}]]\)
\(e j p[[\mathrm{~S} 0!\mathrm{S} 1, \mathrm{~N}, \mathrm{X}]]==e j p[[\mathrm{~S} 0, \mathrm{~N}, \operatorname{ejp}[[\mathrm{~S} 1, \mathrm{~N}, \mathrm{X}]]]]\)
\(e j p[[\mathrm{~S} 0[] \mathrm{S} 1, \mathrm{~N}, \mathrm{X}]]==e j p[[\mathrm{~S} 0, \mathrm{~N}, \mathrm{X}]] \& \& e j p[[\mathrm{~S} 1, \mathrm{~N}, \mathrm{X}]]\)
```

Thus, any command composed only of assignment, skip, raise, assert, assume, var, ;, !, and [], we have:

$$
e j p[[\mathrm{~S}, \mathrm{~N}, \mathrm{X}]]==\text { wlp.S.( } \mathrm{N}, \mathrm{X}, \text { false })
$$

The semantics of the commands loop and call are more elaborate and are described next.

### 2.1 Semantics of loop

The predicate $w l p .(\operatorname{loop}\{\operatorname{inv} \mathrm{J} 1 \ldots \mathrm{Jn}\} \mathrm{S}$ end $) .(\mathrm{N}, \mathrm{X}, \mathrm{W})$ is defined as the weakest predicate P that satisfies the equation:

$$
\mathrm{P}==w l p .(\text { check } \mathrm{J} 1 ; \ldots ; \text { check } \mathrm{Jn} ; \mathrm{S}) .(\mathrm{P}, \mathrm{X}, \mathrm{~W})
$$

Since we don't have a way to compute arbitrary weakest fixpoints, we define the ejp of a loop by desugaring the loop into more primitive guarded commands.

```
\(\operatorname{ejp}[[\operatorname{lomp}\{\operatorname{inv} \mathrm{J} 1 \ldots \mathrm{Jn}\} \operatorname{S}\) end, \(\mathrm{N}, \mathrm{X}]]==\)
    ejp \([[\) DesugarLoop \([[\operatorname{loop}\{\operatorname{inv} \mathrm{J} 1 \ldots \mathrm{Jn}\}\) S end \(]], \mathrm{N}, \mathrm{X}]]\)
```

ESC/Java features two ways to desugar loop, selected by a command-line switch:

```
DesugarLoop[[ Loop, N, X ]] ==
    #if (-loopsafe is used)
    DesugarLoopSafe[[ Loop, N, X ]]
#else
    DesugarLoopFast[[ Loop, N, X ]]
    #end
```

These satisfy, for any loop Loop, and any N, X, and W,

```
wlp.DesugarLoopSafe[[ Loop ]].(N, X, W) ==> wlp.Loop.(N, X, W)
wlp.Loop.(N, X, W) ==> wlp.DesugarLoopFast[[ Loop ]].(N, X, W)
```

We now define the two loop desugarings. The first is defined as follows.

```
DesugarLoopFast[[ loop { inv J1 ... Jn } S end ]] ==
    CheckLoopInvariants[[ J1 ... Jn, "Initially", Loc ]] ;
    S;
    CheckLoopInvariants[[ J1 ... Jn, "AfterIteration", Loc ]] ;
fail
```

where Loc is the source location of the Java loop that gave rise to this loop command, and CheckLoopInvariants is defined as follows:

```
CheckLoopInvariants[[ J1 ... Jn, suffix, Loc ]] ==
    check Loc, ErrorName[[ J1 ]]suffix, Location[[ J1 ]] : Predicate[[ J1 ]];
    ...;
    check Loc,ErrorName[[ Jn ]]suffix, Location[[ Jn ]] : Predicate[[ Jn ]]
```

The other loop desugaring is defined as follows.

```
DesugarLoopSafe[[ loop \{ inv J1 ... Jn \} S end ]] ==
    (CheckLoopInvariants[[ J1 ... Jn, "Initially", Loc ]] ; fail )
[] ( Modify [[ NTargets[[ S, \{\} ]] ]] ;
assume Predicate[[ J1 ]] ; ... ; assume Predicate[[ Jn ]] ;
S;
CheckLoopInvariants[[ J1 ... Jn, "AfterIteration", Loc ]] ;
fail )
```

where Loc is the source location of the Java loop that gave rise to this loop command, and where

```
Modify \([[\{\mathrm{v} 1 \ldots \mathrm{vn}\}]]==\)
    modify \(\mathrm{v} 1 ; \ldots\); modify vn
Modify \([[\) bottom \(]]==\)
    fail
```

where bottom is a special "set" that satisfies the following properties, for any set of variables V (possibly
bottom or $\}$ ):

- bottom $\cup \mathrm{V}==\mathrm{V}$
- $\mathrm{V} \cup$ bottom $==\mathrm{V}$
- bottom $-\mathrm{V}==$ bottom
(It may seem from these properties that bottom equals $\}$. However, bottom is different, because ShakeUp, NTargets, and XTargets treat bottom and $\}$ differently. For example, Modify [ $[\}]$ == skip whereas Modify [[ bottom ]] == fail.)

Functions NTargets and XTargets take two arguments, a guarded command and a set of variables (possibly bottom), and return a set of variables (possibly bottom). Informally, NTargets[ [ $\mathrm{S}, \mathrm{V}]]$ is the set of variables that can be modified as a result of a normal-outcome execution of the command S ; Modify [[ V ]] (where failing is considered not a normal-outcome execution). Similarly, XTargets[[ S, V ]] is the set of variables that can be modified as a result of a exceptional-outcome execution of the command S! (Modify [[ V ]] ; raise) (where failing is considered not an exceptional-outcome execution). Here are their definitions: For any command C,

NTargets[[ C, bottom ]] == bottom
XTargets $[[\mathrm{C}$, bottom $]]==$ bottom
For any set of variables V other than bottom,

```
NTargets[[ v = e, V ]] == V \cup{v}
NTargets[[ v[e0]=e e1, V ]] == V \cup{v}
NTargets[[ v[e0][e1]=e2, V ]]== V \cup{v}
XTargets[[ lhs = e, V ]] == bottom
NTargets[[ skip, V ]] == V
XTargets[[ skip, V ]] == bottom
NTargets[[ raise, V ]] == bottom
XTargets[[ raise, V ]] == V
NTargets[[ assert e, V ]] == V
XTargets[[ assert e, V ]] == bottom
NTargets[[ assume e, V ]] == V
XTargets[[ assume e, V ]] == bottom
    We can do a more precise job for NTargets[[ assume e, V ]], by returning bottom if e is false. Part of this slack is picked up by
    including fail as an actual AST node, rather than as sugar, and generating fail in the translation where we otherwise would have
    hardcoded assume false.
NTargets[[ fail, V ]] == bottom
XTargets[[ fail, V ]] == bottom
NTargets[[ var v1 ...vn in C end, V ]] == NTargets[[ C, V ]] - {v1, .., vn }
XTargets[[ var v1 \ldots.vn in C end, V ]] == XTargets[[ C, V ]] - {v1, ..., vn}
    We require that v1 ... vn not be elements of V.
NTargets[[ C0; C1, V ]] == NTargets[[ C0, NTargets[[ C1, V ]] ]]
XTargets[[ C0; C1, V ]] == XTargets[[ C0, V ]] \cup NTargets[[ C0, XTargets[[ C1, V ]] ]]
NTargets[[ C0! C1, V ]] == NTargets[[ C0, V ]] \cup XTargets[[ C0, NTargets[[ C1, V ]] ]]
XTargets[[ C0!C1,V ]] == XTargets[[ C0, XTargets[[ C1, V ]] ]]
NTargets[[ C0 [] C1, V ]] == NTargets[[ C0, V ]] \cup NTargets[[ C1, V ]]
XTargets[[ C0 [] C1, V ]] == XTargets[[ C0, V ]] \cupXTargets[[ C1, V ]]
NTargets[[ loop { inv J1 ... Jn} C end, V ]] == bottom
XTargets[[ loop {inv J1 ... Jn} C end, V ]] == NTargets[[ C, XTargets[[ C, V ]] ]] \cup XTargets[[ C, V ]]
NTargets[[ call m(e1 ... en), V ]] == V \cup Domain[[ wt ]]
XTargets[[ call m(e1 ... en), V ]] == V \cup Domain[[ wt ]]
```

where wt is the whole-targets map in the whole-targets clause of the method specification returned by GetSpecForCall[[ m, Sc ]], where Sc is the current scope (see below for all of these definitions).

```
Note. A simpler definition of NTargets that seems good enough for the first cut of ESC/Java is the following. Note that there is
then no need for the XTargets function or the bottom value.
NTargets \([[\mathrm{S}, \mathrm{V}]]==\operatorname{SimpleTargets}[[\mathrm{S}]] \cup \mathrm{V}\)
SimpleTargets \([[\mathrm{v}=\mathrm{e}]]==\{\mathrm{v}\}\)
SimpleTargets \([[\mathrm{v}[\mathrm{e} 0]=\mathrm{e} 1]]==\{\mathrm{v}\}\)
SimpleTargets \([[\mathrm{v}[\mathrm{e} 0][\mathrm{e} 1]=\mathrm{e} 2]]==\{\mathrm{v}\}\)
SimpleTargets[[ skip ]] == \{\}
SimpleTargets \([[\) raise \(]]==\{ \}\)
SimpleTargets \([[\) assume e \(]]==\{ \}\)
SimpleTargets[[ fail ]] == \{\}
SimpleTargets \([[\) var \(\mathrm{v} 1 \ldots\) vn in C end \(]]==\operatorname{SimpleTargets}[[\mathrm{C}]]-\{\mathrm{v} 1, \ldots, \mathrm{vn}\}\)
```

```
SimpleTargets[[ C0; C1 ]] == SimpleTargets[[ C0 ]] \cup SimpleTargets[[ C1 ]]
SimpleTargets[[ C0!C1 ]] == SimpleTargets[[ C0 ]] \cup SimpleTargets[[ C1 ]]
SimpleTargets[[ C0 [] C1 ]] == SimpleTargets[[ C0 ]] \cup SimpleTargets[[ C1 ]]
SimpleTargets[[ C0; C1 ]] == SimpleTargets[[ C0 ]] \cup SimpleTargets[[ C1 ]]
SimpleTargets[[ loop {inv J1 ... Jn} C end ]] == SimpleTargets[[ C ]]
SimpleTargets[[ call m(e1 ... en) ]] == Domain[[ wt ]]
```

where wt is as described above.

### 2.2 Semantics of call

The semantics of call $\mathrm{m}(\mathrm{e} 1 \ldots \mathrm{en})$ depends on the method specification associated with m in the scope where the call appears. A scope is the set of declarations visible from a given class (or interface). To describe the semantics of call, we will in this section describe the abstract syntax of a method specification and the desugaring of a call command into more primitive commands. Later in this document (section 7), we describe how the method specification is computed in a given scope.

A method specification has the form:

```
spec T m(p1 \ldots. pn) throws {X1 \ldots. Xx}
precondition P1 ... precondition Pj
targets D1 ... Dk
whole-targets wt
postcondition Q1 ... postcondition Qm
```

In this method specification:

- $m$ is a method name.
- p1 ... pn are formal parameter names, possibly including the special name this.
- T is a result type or void.
- P1 ... Pj are conditions whose predicates' free variables are drawn from the top-level program variables (fields, static fields, and special program variables like elems and alloc) and p1 ... pn. Those conditions whose error name is Free are called free preconditions; the others are called checked preconditions.
- D1 ... Dk are designator expressions (that is, guarded command lhs's) known as target designators.
- wt is a map from variables to variables. In particular, wt maps the set of variables one gets from "shaving" the target designators D1 ... Dk to similar variables adorning with the suffix @pre (see section 7.2.0). "Whole targets" refers to the variables in the domain of wt.
- Q1 ... Qm are conditions, the free variables of whose predicates are drawn from the top-level program variables, $\mathrm{p} 1 \ldots \mathrm{pn}$, the variables in image of wt , and the special result variables $E C, R E S$, and XRES. Those conditions whose error name is Free are called free postconditions; the others are called checked postconditions.

We consider $\mathrm{p} 1 \ldots \mathrm{pn}$ and the variables in the image of wt to be bound within the method specification. All other free variables are either static fields, instance variables, or special variables. The variables in the image of wt do not occur in the list of target designators, despite the fact that any index expression occurring in a target designator refers to the value of the index expression in the pre-state.

Usually, the formal parameter names p1 ... pn correspond to formal parameters declared by the programmer. For instance methods, however, p 1 is the special variables this and $\mathrm{p} 2 \ldots \mathrm{pn}$ correspond to the formal parameters declared by the programmer.

All preconditions P1 ... Pj are assumed on entry to implementations, but only the checked preconditions are checked at call sites. The free preconditions need not be checked at call sites because they are guaranteed by the Java type system and other checking mechanisms (like non_null). Similarly, all postconditions Q1 ... Qm are assumed after calls, but only the checked postconditions are checked on exit from implementations. The free postconditions need not be checked on exit from implementations because they are guaranteed by the Java type system and other checking mechanisms.

Given that m is a method name associated in the current scope with the template method specification above, the command call $\mathrm{m}(\mathrm{e} 1 \ldots \mathrm{en})$ occurring at a location $L$ desugars as follows:

```
var p1@L ... pn@L in
    p1@L=e1;...;pn@L=en ;
    check L, P1 ; .. ; check L, Pj ;
    Note that the check desugars to skip for free preconditions.
    var pt[[ Image[[ wt ]] ]] in
    #for w in Domain[[ wt ]] do
        assume pt[[ wt[[ w ]] ]] == w ;
    Do we get better performance if instead of this assumption we do the semantically equivalent assignment pt[[wt[[w]]]] =w ?
    #end
    modify IndexSubst[[ D1, pt ]] ; .. ; modify IndexSubst[[ Dk, pt ]] ;
    modify EC; modify RES; modify XRES;
    assume pt[[ Predicate[[ Q1 ]] ]] ; ... ; assume pt[[ Predicate[[ Qm ]] ]] ;
    #if ({X1 ... Xx } is nonempty)
    The reason for producing the following command only conditionally is one of concern for performance: It would be correct, but
    we conjecture inefficient, to always emit the following command.
        (assume EC== ec$return [] assume EC ==ec$throw; raise )
        #end
    end
end
```

in which pt is the map $\{\mathrm{p} 1 \mathrm{p} 1 @ \mathrm{~L}, \ldots, \mathrm{pn} \mathrm{pn} @ \mathrm{~L}\} \cup \operatorname{Remap}[[\mathrm{wt}, \mathrm{L}]]$, where

```
Remap[[ wt, L ]] ==
    #for w in Domain[[ wt ]] do
        {wt[[[w]] w@L}\cup
    #end
```

And where IndexSubst is defined as follows:

```
IndexSubst \([[\mathrm{g}, \mathrm{pt}]]==\)
    g
IndexSubst \([[\mathrm{f}[\mathrm{E}], \mathrm{pt}]]==\)
    \(\mathrm{f}[\mathrm{pt}[[\mathrm{E}]]]\)
```

IndexSubst $[[\mathrm{e}[\mathrm{E} 0][\mathrm{E} 1]$, pt $]]==$
$\mathrm{e}[\mathrm{pt}[[\mathrm{E} 0]]][\operatorname{pt}[[\mathrm{E} 1]]]$

## 3 Special variables and literals

The translation introduces several special variables and literals.
The special variables $E C$ (exception code), $R E S$, and $X R E S$ are used is the translation of return, throw, break, continue, and method calls, all of which give rise to uses of the guarded command raise. By convention, the guarded commands generated by the translation always set $E C$ (and possibly $R E S$ or $X R E S$ ) before performing a raise. The enclosing exception handler (that is, the command T in $\mathrm{S}!\mathrm{T}$ ) then tests $E C$ (and possibly RES or XRES) when determining how to proceed.

More specifically, before a raise that corresponds to a Java return, the guarded command sets $E C$ to the special literal ec\$return and sets $R E S$ to the return value, if there is one. Before a raise that corresponds to a Java throw, the guarded command sets $E C$ to the special literal ec\$throw and sets XRES to the exception
thrown. The translation of a method call uses a combination of these. Before a raise that corresponds to a Java break $L$, the guarded command sets $E C$ to L. Finally, before a raise that corresponds to a Java continue L , the guarded command sets $E C$ to continue $\$ \mathrm{~L}$, which is a name derived from the name L .

The special variable elems models the state of all arrays.
The special variable alloc represents the current allocation time.
The special variable $L S$ represents the set of locks held by the current thread.

## 4 Translating expressions

In this section, we describe the translation of Java expressions. Since Java expressions may have side effects and guarded command expressions must not, it is occasionally necessary to introduce temporary variables. For example, the Java expression

$$
x+=(x=3) ;
$$

may be translated into the guarded command

$$
\text { var old } x \text { in old } x=x ; x=3 ; x=\operatorname{old} x+x \text { end }
$$

Our translation introduces temporary variables where these may be useful. Throughout the translation, we assume that the temporary variables introduced have fresh names; the choice of these names may affect the readability of satisfying assignments, but we not address that issue here.

In this section, we define a translation function TrExpr for expressions. The signature of this function is $\operatorname{Tr} \operatorname{Expr}[[\mathrm{E}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]$, where E is a Java expression, p is a set of protect expressions (defined below), V is a set of temporary variable names, and $r$ is a guarded command expression. $E$ and $p$ are in-parameters, $V$ is an in-out-parameter, and r is an out-parameter. $\operatorname{Tr} \operatorname{Expr}[[\mathrm{E}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]$ returns a guarded command C that essentially evaluates the side effects of $E$, raises any exception raised by $E$, and causes any error of $E$. This command may include assignments to freshly generated temporary variables; as a side effect, TrExpr adds these temporary variables to V . Another side effect of TrExpr is to set r to an guarded command expression whose value in the normal post-state of $C$ corresponds to the Java value of $E$. The expression $r$ has the property of being insensitive to side effects of any protect expression in $p$.

A protect expression is either a Java expression or something of the form $F=$, where $F$ is map variable. An expression $e$ is insensitive to side effects of a Java expression $E$ when no normally terminating evaluation of $E$ can change the value of $e$. An expression $e$ is insensitive to side effects of $F=$ when it is insensitive to arbitrary modifications of $F$.

Before defining TrExpr, we describe three subroutines of which we will make frequent use, Clash, Impure, and Protect.

For any guarded command expression e and any protect expression $q, C l a s h[[\mathrm{e}, \mathrm{q}]]$ must be true if e is sensitive to any side effect of q , but is allowed to be true more often than that. For now, Clash is conservatively defined as follows: For any Java expression E and map variable F,
$\operatorname{Clash}[[\mathrm{e}, \mathrm{E}]]==$
(e mentions any Java non-final local variable, non-final field, elems, alloc, or RES) \&\& Impure [[ E ]]
$\operatorname{Clash}[[\mathrm{e}, \mathrm{F}=]]==$
(e mentions F)
In future versions of ESC/Java, we may use a more aggressive definition of Clash.
For any Java expression E, Impure[[ E ]] is true if E contains any

- assignment ( $=,+=$, etc.),
- pre-increment, pre-decrement, post-increment, post-decrement (++ or --),
- object creation (new), or
- method invocation.

Note that the possibility of raising an exception or going wrong does not imply that an expression is impure; only state changes do.

The signature of Protect is Protect $[[\mathrm{e}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]$, where e is a guarded command expression, and $\mathrm{p}, \mathrm{V}$, and r are as in the signature of TrExpr. In a nut shell, Protect sets r to an expression that is equivalent to e, but is insensitive to side effects of the protect expressions in $p$. In doing so, it may make use of a temporary variable $v$, which it adds to V , and generate (i.e., return) a guarded command that assigns the value e to $v$.

```
\(\operatorname{Protect}[[\mathrm{e},\{\mathrm{E} 1 \ldots \mathrm{En}\}, \mathrm{V}, \mathrm{r}]]==\)
    \#if (Clash[[ e, E1 ]] || ... || Clash[[ e, En ]])
    \(\# \mathrm{~V}=\mathrm{V} v\);
    \(\# \mathbf{r}=v\);
    \(v=\mathrm{e}\);
    \#else
    \(\# \mathrm{r}=\mathrm{e}\);
    \#end
```

An explanation of our notation is in order. We use assignment statements where the left-hand side begins with a \# to denote meta-assignments. Variables type set in italics denote fresh guarded command variables. Lines that don't begin with \# (like the assignment $v=\mathbf{e}$; in this example) show a guarded command fragment returned by Protect.

[^1]In the translation below, we use $\mathrm{x}, \mathrm{xj}$ to denote variables, $\mathrm{E}, \mathrm{Ej}$ to denote Java expressions, C to denote any literal, and T to denote a type.

```
\(\operatorname{Tr} \operatorname{Expr}[[\) this, \(\mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    \(\# \mathbf{r}=\) this
\(\operatorname{TrExpr}[[\mathrm{C}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    \(\# \mathrm{r}=\mathrm{C}\)
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{x}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    ReadCheck \([[\mathrm{x}]]\);
    \(\operatorname{Protect}[[\mathrm{x}, \mathrm{p}, \mathrm{V}, \mathrm{r}]]\)
where
ReadCheck \([[\mathrm{x}]]==\)
    \#if (x declared with uninitialized)
    check InitializationViolation: init\$x ;
    \#end
```

```
#if (X declared with defined_if P)
    check DefinednessViolation: TrSpecExpr[[ P ]] ;
#end
#if (x declared with the monitored_by expressions MU1 ... MUn where 0<n)
    check SharingViolation:
            (TrSpecExpr[[ MU1 ]] != null && LS[ TrSpecExpr[[ MU1 ]] ]) |
                    ...|
                    (TrSpecExpr[[ MUn ]] != null && LS[ TrSpecExpr[[ MUn ]] ]);
#end
TrExpr[[ E0[E1], p, V, r ]] ==
    #var e0 e1 in
    TrExpr[[ E0, {E1}, V, e0 ]];
    TrExpr[[ E1, {}, V, e1 ]];
    ArrayAccessCheck[[ e0, e1 ]];
    Protect[[ elems[e0][e1], p, V, r ]]
    #end
```

where

```
ArrayAccessCheck[[ e0, e1 ]] ==
    check NullPointerException : e0 != null ;
    check IndexOutOfBoundsExceptionLower : 0<= e1;
    check IndexOutOfBoundsExceptionUpper : e1 < array$length(e0)
TrExpr[[ E.F, p, V,r ]] ==
    #var e in
        TrExpr[[ E, {}, V, e ]];
    check NullPointerException: e != null;
    ReadCheck[[F[e] ]];
    Protect[[ F[e], p, V, r ]]
    #end
```

where
ReadCheck $[[\mathrm{F}[\mathrm{e}]$ ] $==$
\#if (F declared with defined_if P )
check DefinednessViolation : TrSpecExpr $\left[\left[\begin{array}{ll}P,\{\text { this } & e\end{array},\{ \}\right]\right]$;
\#end
\#if (F declared with the monitored and monitored_by expressions MU1 ... MUn where $0<\mathrm{n}$ )
check SharingViolation:
(TrSpecExpr[[ MU1, \{this e\}, \{\} ]] != null \&\& LS[ $\operatorname{TrSpecExpr[[~MU1,~\{ this~e\} ,~\{ \} ~]]~])~||~}$
... ||
(TrSpecExpr[[ MUn, \{this e\}, \{\} ]] != null \&\& $L S\left[\operatorname{TrSpecExpr}\left[\left[\begin{array}{cc}\text { MUn, }\{\text { this } \quad \mathrm{e}\},\{ \}]]\end{array}\right]\right.\right.$;
\#end
$\operatorname{Tr} \operatorname{Expr}[[$ unaryOp E, p, V, r ]] ==
\#var e in
$\operatorname{Tr} \operatorname{Expr}[[\mathrm{E},\{ \}, \mathrm{V}, \mathrm{e}]] ;$
$\operatorname{Protect}[[$ unaryOp(e), p, V, r ]]
\#end
$\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0 \operatorname{binOp} \mathrm{E} 1, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==$
\#var e0 e1 in
$\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0,\{\mathrm{E} 1\}, \mathrm{V}, \mathrm{e} 0]]$;
$\operatorname{Tr} E x p r[[\mathrm{E} 1,\{ \}, \mathrm{V}, \mathrm{e} 1]]$;
\#if (binOp is integer / or integer \%)

```
        check ArithmeticException: e1 != 0;
        #end
        Protect[[ binOp(e0, e1), p, V, r ]]
    #end
TrExpr[[ E0 || E1, p, V, r ]] ==
    #var e0 e1 in
        TrExpr[[ E0, {E1}, V, e0 ]];
        if ! e0 then
            TrExpr[[ E1, {}, V, e1 ]]
    end;
    Protect[[ bool$or(e0, e1), p, V, r ]]
#end
TrExpr[[ E0 && E1, p, V, r ]] ==
    #var e0 e1 in
        TrExpr[[ E0, {E1}, V, e0 ]];
        if e0 then
            TrExpr[[ E1, {}, V, e1 ]]
    end;
    Protect[[ bool$and(e0, e1), p, V, r ]]
    #end
TrExpr[[(E0 ? E1 : E2), p, V, r ]] ==
    #var e0 e1 e2 in
        TrExpr[[ E0, {E1, E2}, V, e0 ]];
        if e0 then
            TrExpr[[ E1, {}, V, e1 ]]
        else
            TrExpr[[ E2, {}, V, e2 ]]
        end ;
        Protect[[ term$conditional(e0, e1, e2), p, V, r ]]
    #end
TrExpr[[ newarray T E1 E2 ... En, p, V,r ]] ==
    #var e1 e2 ... en in
        TrExpr[[ E1, {E2 ... En}, V, e1 ]];
        TrExpr[[ E2, {E3 ... En}, V, e2 ]];
        ...;
        TrExpr[[ En, {}, V, en ]];
        #V = V a alloc';
        assume array$fresh(a, alloc, alloc', elems,
                shapeMore(e1, shapeMore(e2, ...(shapeOne(en))...)),
                array(array(...(array(T))...)), zero) ;
    alloc = alloc';
    #r =a
#end
```

The number of applications of array around T in this assumption is n . The meta variable zero denotes the zero-equivalent value for type $T$.

```
TrExpr[[ array T E1 E2 ... En, p, V, r ]] ==
    #var e1 e2 ... en in
    TrExpr[[ E1, {E2 ... En}, V, e1 ]];
    TrExpr[[ E2, {E3 ... En}, V, e2 ]];
    ...;
    TrExpr[[ En, {}, V, en ]];
    #V = V a alloc';
```

```
    assume alloc < vAllocTime(a) && vAllocTime(a)< alloc';
    assume a!= null && typeof(a)== array ( }\textrm{T})&&\operatorname{array$length}(a)==\textrm{n}\mathrm{ ;
    assume elems[a][0]== e1 && ...&& elems [a][n-1]== en ;
    alloc = alloc';
    #r = a
#end
TrExpr[[ E instanceof T, p, V, r ]] ==
    #var e in
    TrExpr[[ E, {}, V, e ]];
    Protect[[ is(e, T), p, V, r ]]
#end
TrExpr[[(T) E, p, V, r ]] ==
#var e in
    TrExpr[[ E, {}, V, e ]];
    #if (T is an object type)
            check ClassCastException: is(e, T)
            Protect[[ e, p, V, r ]]
        #else
            Protect[[ cast(e, T), p, V, r ]]
        #end
#end
```


### 4.0 Assignment expressions

There are three kinds of assignment operators, namely direct assignment (as in $x=6$ ), update assignment (as in $x+=6$ ), and post-update assignment (as in $x++$ ). There are also three kinds of l-values, namely variables (as in $x=6$ ), instance variables (as in $o f=6$ ), and array elements (as in $a[i]=6$ ). So, all in all, we consider nine cases. This results in some duplication, but we felt that this would increase clarity (and besides, $3 * 3$ is not that much larger than $3+3$ ).

```
TrExpr[[ x = E, p, V,r ]] ==
    #var e in
        TrExpr[[ E, {}, V, e ]];
        WriteCheck[[ x, e ]];
        x = e ;
        #if (x declared with uninitialized)
        init$x = bool$true;
    #end
    Protect[[ x, p, V, r ]]
    #end
        This comes from [JLS, 15.25.1].
```

where
WriteCheck $[[\mathrm{x}, \mathrm{e}]]==$
\#if (x declared with non_null)
check NullAssignmentViolation : e != null ;
\#end
\#if (x declared with the monitored_by expressions MU1 ... MUn where $0<n$ )
check SharingViolation :
(TrSpecExpr[[ MU1 ]] != null || ... || TrSpecExpr[[ MUn ]] != null) \&\&
$(\operatorname{TrSpecExpr}[[\mathrm{MU1}]]==$ null $\| L S[\operatorname{TrSpecExpr}[[\mathrm{MU1}]]$ ] $) \& \&$
... \&\&
$(\operatorname{TrSpecExpr}[[\mathrm{MUn}]]==$ null $\| \operatorname{LS[\operatorname {TrSpecExpr}[[\mathrm {MUn}]]}])$;
\#end

```
TrExpr[[ x binOp= E, p, V, r ]] ==
    #var old e in
        ReadCheck[[ x ]];
        Protect[[ x, {E}, V, old ]];
        TrExpr[[ E, {}, V, e ]];
        #if (binOp is integer / or integer %)
        check ArithmeticException: e != 0;
    #end
    #if (range type of binOp is the static type of x)
        WriteCheck[[ x, binOp(old, e) ]];
        x = binOp(old, e);
    #else
            WriteCheck[[ x, cast(binOp(old, e), T) ]] ; // where T denotes the static type of x
        x = cast(binOp(old, e), T) ;
    #end
    #end
    Protect[[ x, p, V, r ]]
    This comes from [JLS, 15.25.2].
    Note that we need not set init$x to true, since the ReadCheck has checked that it is already true.
    Section [JLS, 15.25] says that the result of this assignment expression is the value of the variable after the assignment has
    occurred; hence, we return x instead of binOp(old, e).
TrExpr[[ x binOp, p, V, r ]] ==
    ReadCheck[[ x ]];
    #V = V old ;
    old = X ;
    WriteCheck[[ x, binOp(x, 1)]];
    x = binOp(x, 1);
    #r = old
        Note that we need not set init$x to true, since the ReadCheck has checked that it is already true.
        Note that this translation ignores the possibility of wrap-around.
TrExpr[[ E0.F = E1, p, V,r ]] ==
    #var e0 e1 in
    TrExpr[[ E0, {E1, F=}, V, e0 ]];
    check NullPointerException: e0 != null ;
    TrExpr[[ E1, {}, V, e1 ]];
    WriteCheck[[ F[e0], e1 ]];
    F[e0]=e1;
    Protect[[ F[e0], p, V, r ]]
    #end
    The ordering of the checks is spelled out in [JLS, 15.25.1].
```

where

```
WriteCheck[[ F[e0], e1 ]] ==
    #if (F declared with non_null)
    check NullAssignmentViolation : e1 != null ;
    #end
    #if (F declared with the monitored and monitored_by expressions MU1 ... MUn where 0<n)
        check SharingViolation:
                            (TrSpecExpr[[ MU1, {this e0}, {} ]] != null | ...| TrSpecExpr[[ MUn, {this e0}, {} ]] != null)
                    &&
                    (TrSpecExpr[[ MU1, {this e0}, {} ]] == null |LS[ TrSpecExpr[[ MU1, {this e0}, {} ]] ]) &&
            ... &&
            (TrSpecExpr[[ MUn, {this e0}, {} ]] == null |LSS[TrSpecExpr[[ MUn, {this e0}, {} ]] ]);
    #end
```

```
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0 . \mathrm{F} \operatorname{binOp}=\mathrm{E} 1, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    \#var e0 old e1 in
    \(\operatorname{Tr} E x p r[[\mathrm{E} 0,\{\mathrm{E} 1, \mathrm{~F}=\}, \mathrm{V}, \mathrm{e} 0]]\);
    check NullPointerException: e0 != null;
    ReadCheck[[ F[e0] ]] ;
    Protect [[ F[e0], \{E1\}, V, old ]] ;
    \(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 1,\{ \}, \mathrm{V}, \mathrm{e} 1]]\);
    \#if (binOp is integer / or integer \%)
        check ArithmeticException: e1 != 0 ;
    \#end
    \#if (range type of binOp is the static type of EO.F)
        WriteCheck [[ F[e0], binOp(old, e1) ]] ;
        F[e0] = binOp(old, e1);
    \#else
        WriteCheck \([[\mathrm{F}[\mathrm{e} 0]\), cast(binOp(old, e1), T) ]] ; // where T denotes the static type of E0.F
        \(\mathrm{F}[\mathrm{e} 0]=\operatorname{cast}(\mathrm{binOp}(\mathrm{old}, \mathrm{e} 1), \mathrm{T})\);
    \#end
    \(\operatorname{Protect}[[\mathrm{F}[\mathrm{eO}], \mathrm{p}, \mathrm{V}, \mathrm{r}]]\)
    \#end
        This comes from [JLS, 15.25.2].
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} . \mathrm{F}\) binOp, p, V, r ]] ==
    \#var e in
        \(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E},\{\mathrm{F}=\}, \mathrm{V}, \mathrm{e}]]\);
        check NullPointerException : e != null;
        \#V = V old ;
        ReadCheck[[ \(\mathrm{F}[\mathrm{e}]\) ]];
        old \(=\mathrm{F}[\mathrm{e}]\);
        WriteCheck[[ \(\mathrm{F}[\mathrm{e}]\), \(\operatorname{binOp}(\) old, 1\()]]\);
        \(\mathrm{F}[\mathrm{e}]=\operatorname{binOp}(\) old, 1\()\);
    \(\# \mathrm{r}=\) old
\#end
        Note that this translation ignores the possibility of wrap-around.
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0[\mathrm{E} 1]=\mathrm{E} 2, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    \#var e0 e1 e2 in
        \(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0,\{\mathrm{E} 1, \mathrm{E} 2\), elems \(=\}, \mathrm{V}, \mathrm{e} 0]]\);
        \(\operatorname{TrExpr}[[\mathrm{E} 1,\{\mathrm{E} 2\), elems \(=\}, \mathrm{V}, \mathrm{e} 1]]\);
    \(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 2,\{ \}, \mathrm{V}, \mathrm{e} 2]]\);
    ArrayAccessCheck[[ e0, e1 ]];
    \#if (static element type of E0 is a non-final object type)
        check ArrayStoreException : is(e2, elemType(typeof(e0))) ;
    \#end
    elems \([\mathrm{e} 0][\mathrm{e} 1]=\mathrm{e} 2\);
    \(\operatorname{Protect}[[\) elems \([\mathrm{e} 0][\mathrm{e} 1], \mathrm{p}, \mathrm{V}, \mathrm{r}]]\)
\#end
        The order of evaluation and checking (in particular, that E2 is evaluated before before any array access check is done) is
        specified in \([J L S, 15.25 .1]\). Note that this is different from the order in which evaluation and checking is done for E0.F \(=E 1\), see
        above. It is also different from the order in which this check is done in the next case, \(\mathrm{E} 0[\mathrm{E} 1]\) binOp= E 2 [JLS, 15.25.2]. The
        reason for this wisdom is unbeknownst to us.
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 0[\mathrm{E} 1] \operatorname{binOp}=\mathrm{E} 2, \mathrm{p}, \mathrm{V}, \mathrm{r}]]==\)
    \#var e0 e1 old e2 in
        \(\operatorname{TrExpr}[[\mathrm{E} 0,\{\mathrm{E} 1, \mathrm{E} 2\), elems \(=\}, \mathrm{V}, \mathrm{e} 0]]\);
        \(\operatorname{TrExpr}[[\mathrm{E} 1,\{\mathrm{E} 2\), elems=\}, V, e1 ]];
        ArrayAccessCheck[[ e0, e1 ]];
        \(\operatorname{Protect}[[\) elems \([\mathrm{e} 0][\mathrm{e} 1],\{\mathrm{E} 2\}, \mathrm{V}\), old \(]]\);
        \(\operatorname{TrExpr}[[\mathrm{E} 2,\{ \}, \mathrm{V}, \mathrm{e} 2]]\);
        \#if (binOp is integer / or integer \%)
```

```
        check ArithmeticException: e2 != 0;
    #end
    #if (range type of binOp is the static type of EO[E1])
        elems[e0][e1] = binOp(old, e2) ;
    #else
        elems[e0][e1] = cast(binOp(old, e2), T);// where T denotes the static type of E0[E1]
    #end
    Protect[[ elems[e0][e1], p, V, r ]]
#end
    This comes from [JLS, 15.25.2].
TrExpr[[ E0[E1] binOp, p, V, r ]] ==
    #var e0 e1 in
        TrExpr[[ E0, {E1, elems=}, V, e0 ]];
        TrExpr[[ E1, {elems=}, V, e1 ]];
        ArrayAccessCheck[[ e0, e1 ]];
    #V = V old ;
    old = elems[e0][e1];
    elems[e0][e1] = binOp(old,1);
    #r = old
#end
    Note that this translation ignores the possibility of wrap-around.
```


### 4.1 Method call expressions

Java features a number of different call expressions, namely instance method calls, static method calls, and constructor calls. (There are also constructor call statements. These will be described in the section 6 on statements.)

The abstract syntax of an instance method is:
Expr . Identifier (Expr*)
We treat the Expr before the "." as a parameter of the call.
The abstract syntax of a static method call can be one of:
Identifier (Expr*)
Expr.Identifier (Expr*)
super . Identifier (Expr*)
In the two latter cases, what goes before the "." is not a parameter of the call.
The abstract syntax of a class instance creation expression [JLS, 15.8] is:
new Type Identifier (Expr*)
We treat this simply as a constructor invocation.
The translation of a method invocation or constructor invocation emits a code fragment containing a call command.

```
TrExpr[[m(E1 E2 ... En), p, V, r ]] ==
    #var e1... en in
        TrExpr[[ E1, {E2 .. En}, V, e1 ]] ; ...; TrExpr[[ En, {}, V, en ]];
        call m(e1 .. en) ;
        Protect[[ RES, p, V, r ]]
    #end
TrExpr[[ E0.m(E1 E2 ... En), p, V, r ]] ==
    #var e0 ... en in
        #if (m is a static method)
        TrExpr[[ E0, {}, V, e0 ]];
    #else
        TrExpr[[ E0, {E1 .. En}, V, e0 ]];
```

```
    #end
    TrExpr[[ E1, {E2 ... En}, V, e1 ]] ; .. ; TrExpr[[ En, {}, V, en ]];
    #f( (m is a static method)
        call m(e1 ... en) ;
    #else
        call m(e0 e1 ... en);
    #end
    Protect[[ RES, p, V, r ]]
#end
TrExpr[[ super.m(E1 E2 ... En), p, V, r ]] ==
    #var e1 ... en in
        TrExpr[[ E1, {E2 .. En}, V, e1 ]] ; ... ; TrExpr[[ En, {}, V, en ]];
        #if (m is a static method)
        call m(e1 ... en);
    #else
        call m(this e1 ... en) ;
    #end
    Protect[[ RES, p, V, r ]]
#end
TrExpr[[ new T m (E1 E2 ... En), p, V, r ]] ==
    #var e1 ... en in
        TrExpr[[ E1, {E2 ... En}, V, e1 ]] ; .. ; TrExpr[[ En, {}, V, en ]];
        call m(e1 ... en) ;
    assume typeof(RES)== T;
    Protect[[ RES, p, V, r ]]
    #end
```


## 5 Translating specification expressions

This section describes a function $\operatorname{TrSpec} E x p r$ that translates a specification expression into a guarded command expression. Recall from ESCJ 17, ESC/Java Annotation Reference Manual, specification expressions are similar to Java expressions, but they are pure (that is, they are side-effect free), they cannot raise exceptions, they are total (that is, their evaluation cannot "go wrong"), and they may include additional constructs such as quantifiers and $P R E$ and $f r e s h$. Guarded command expressions are similar to specification expressions in that they are pure and total and may include quantifiers. However, guarded command expressions do not include $P R E$ and fresh, for example.

Function $\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]]$, where E is an specification expression and sp and st are domaindisjoint partial maps from variables to guarded command expressions, returns a guarded command expression corresponding to E , in which every occurrence of a variable v in E and in Domain $[[\mathrm{sp}]]$ has been replaced by $s p[[\mathrm{v}]]$, and every occurrence of a variable v in a $P R E$ expression in E and in Domain [[st]] has been replaced by $\operatorname{st[[v]].~We~require~that~if~} \mathrm{E}$ contains a fresh expression, then alloc is in Domain [[st]].

In other parts this document, as a notational convenience, we write $\operatorname{TrSpecExpr}[[\mathrm{E}]]$ for $\operatorname{TrSpecExpr}[[\mathrm{E}$, $\},\{ \}]]$. Here, as a notational convenience, we abuse the notation $\mathrm{sp}[[\mathrm{v}]]$ to mean
\#if (v in Domain[[sp]])
$\mathrm{sp}[[\mathrm{v}]]$
\#else
v
\#end
and similarly for $s t$.
$\operatorname{TrSpecExpr}[[$ this, sp, st ]] $==$ sp[[this]]

```
TrSpecExpr[[ C, sp, st]] == /* where C is a literal */
```

C
$\operatorname{TrSpecExpr}[[\mathrm{v}, \mathrm{sp}, \mathrm{st}]]==/ *$ where v is a local variable, parameter, static field, $R E S$, or $L S$ */
$\mathrm{sp}[[\mathrm{v}]]$
$\operatorname{TrSpecExpr}[[\mathrm{E} . \mathrm{g}, \mathrm{sp}, \mathrm{st}]]==/ *$ where g is a static field $* /$
sp[[g]]
$\operatorname{TrSpecExpr}[[\mathrm{E} . \mathrm{f}, \mathrm{sp}, \mathrm{st}]]==/ *$ where f is an instance variable */
sp[[f]] [ $\operatorname{TrSpecExpr[[E,~sp,~st~]]~]~}$
TrSpecExpr[[ E0[E1], sp, st ]] ==
$\mathrm{sp}[[$ elems $]][\operatorname{TrSpec} E x p r[[\mathrm{E} 0, \mathrm{sp}, \mathrm{st} \mathrm{]]}][\operatorname{TrSpecExpr}[[\mathrm{E} 1, \mathrm{sp}, \mathrm{st}]]]$
$\operatorname{TrSpecExpr}[[\mathrm{E}[*], \mathrm{sp}, \mathrm{st}]]==$
sp[[elems]] [ TrSpecExpr[[ E, sp, st ]] ]
$\operatorname{TrSpec} \operatorname{Expr}[[$ unOp E, sp, st $]]==/ *$ where unOp is a unary operator, possibly typeof or elemtype or min */
unOp( $\operatorname{TrSpecExpr}[[$ E, sp, st ]] $)$
$\operatorname{TrSpecExpr}[[\mathrm{E} 0 \mathrm{binOp} \mathrm{E} 1, \mathrm{sp}, \mathrm{st}]]==/ *$ where binOp is a binary operator, possibly \&\& or $\|$ or $==>$ or $<$ : */
$\operatorname{binOp}(\operatorname{TrSpecExpr}[[\mathrm{E} 0, \mathrm{sp}, \mathrm{st}]], \operatorname{TrSpecExpr}[[\mathrm{E} 1, \mathrm{sp}, \mathrm{st}]])$
Here, we are using prefix notation for applications of all binary operators. Elsewhere in this document, we frequently use infix notation.
$\operatorname{TrSpecExpr}[[\mathrm{G}$ ? E0: E1, sp, st ]] ==
term $\$$ conditional ( $\operatorname{TrSpecExpr}[[\mathrm{G}, \mathrm{sp}, \mathrm{st}]], \operatorname{TrSpecExpr}[[\mathrm{E} 0, \mathrm{sp}, \mathrm{st}]], \operatorname{TrSpecExpr}[[\mathrm{E} 1, \mathrm{sp}, \mathrm{st}]]$ )
$\operatorname{TrSpecExpr}[[\mathrm{E}$ instanceof T, sp, st ]] ==
is( TrSpecExpr[[ E, sp, st ]], TrType[[ T ]] )
$\operatorname{TrSpecExpr}[[(\mathrm{T}) \mathrm{E}, \mathrm{sp}, \mathrm{st}]]==$ $\operatorname{cast}(\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]], \operatorname{Tr} \operatorname{Type}[[\mathrm{T}]])$
$\operatorname{Tr} T y p e[[\mathrm{~T}]]==/ *$ where T is a primitive type or declared type */
T
$\operatorname{TrType}[[\mathrm{T}[]]]==$
$\operatorname{array}(\operatorname{TrType}[[\mathrm{T}]])$
$\operatorname{TrSpecExpr}[[(\mathbf{f o r a l l}(\mathrm{T} 1 \times 1) \ldots(\mathrm{Tn} \mathrm{xn}) \mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
$/ *$ where we require the domains of $s p$ and st to be disjoint from $\{x 1, \ldots, x n\}^{* /}$ We believe our translation never violates this requirement, but it might be worthwhile to include a runtime check in the translator.
(forall $\mathrm{x} 1 \ldots \mathrm{xn}::$ TypeCorrectAs $[[\mathrm{x} 1, \mathrm{~T} 1]] \& \& \ldots \& \&$ TypeCorrectAs[[ $\mathrm{xn}, \mathrm{Tn}]]$
$==>\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]]$ )
We should also replace occurrences of alloc in TypeCorrectAs[[ x1, T1 ]] \&\& $\ldots \& \& \operatorname{TypeCorrectAs[[\mathrm {xn},\mathrm {Tn}]]\text {with}\mathrm {sp}[[~}$ alloc ]].

TypeCorrectAs $[[\mathrm{v}, \mathrm{T}]]==$
TypeAndNonnullCorrectAs[[ $\mathrm{v}, \mathrm{T}$, false ]]
TypeAndNonnullCorrectAs $[[\mathrm{v}, \mathrm{T}$, isNonNull $]]==$
$i s(\mathrm{v}, \mathrm{T})$
\#if ( T is a reference type)
\&\& allocTime $(\mathrm{v})<$ alloc

```
    #if (isNonNull)
        && v != null
    #end
#end
    An optimization would be to generate typeof(v) <: T instead of is(v, T) if T is a reference type and isNonNull is true.
```

$\operatorname{TrSpecExpr}[[($ exists (T1 x1) $\ldots(\mathrm{Tn} \mathrm{xn}) \mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
$/^{*}$ where we require the domains of sp and st to be disjoint from $\{\mathrm{x} 1, \ldots, \mathrm{xn}\}^{* /}$ We believe our translation never violates this requirement, but it might be worthwhile to include a runtime check in the translator.
(exists $\mathrm{x} 1 \ldots \mathrm{xn}::$ TypeCorrectAs[[ x1, T1 ]] \&\& ... \&\& TypeCorrectAs[[ xn, Tn ]] $\& \& \operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]])$
We should also replace occurrences of alloc in TypeCorrectAs[[ x1, T1 ]] \&\& ... \&\& TypeCorrectAs[[ $\mathrm{xn}, \mathrm{Tn}]]$ with sp[ alloc ]].
$\operatorname{Tr} \operatorname{Spec} E x p r[[(\operatorname{lblpos} \mathrm{~L} \mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
(lblpos L TrSpecExpr[[ E, sp, st ]] )
$\operatorname{Tr} \operatorname{Spec} E x p r[[(\operatorname{lbIneg} \mathrm{~L} \mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
(lblneg L TrSpecExpr[[ E, sp, st ]] )
$\operatorname{TrSpecExpr}[[\operatorname{PRE}(\mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
$\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp} \cup \mathrm{st},\{ \}]]$
It is okay to pass the empty map as the third parameter because our annotation language forbids uses of $P R E$ or fresh within an argument of $P R E$.
$\operatorname{TrSpecExpr}[[\operatorname{fresh}(\mathrm{E}), \mathrm{sp}, \mathrm{st}]]==$
$\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]]$ != null \&\& st[[alloc]] < allocTime( $\operatorname{TrSpecExpr[[~E,~sp,~st~]]~)~}$ We omit the requirement allocTime ( $\operatorname{TrSpecExpr}[[\mathrm{E}, \mathrm{sp}, \mathrm{st}]]$ ) <alloc because this condition is introduced by other mechanisms when it is needed.

## 6 Translating statements

$\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]]$, where S is a Java statement and V is a set of temporary variable names, translates S into a guarded command. Temporary variables used in that command can either be local to the command or added to the in-out parameter V . We assume again that variables introduced in translation are fresh.
$\operatorname{TrStmt}[[$ block S1 ... Sn end, V ] ] ==
var x1 ... xk init\$xi ... init\$xj in
$\operatorname{TrStmt}[[\mathrm{S} 1, \mathrm{~V}]] ; \ldots ; \operatorname{TrStmt}[[\mathrm{Sn}, \mathrm{V}]]$
end
where $\mathrm{x} 1 \ldots \mathrm{xk}$ are the variables introduced by those of the statements $\mathrm{S} 1 \ldots \mathrm{Sn}$ that are Java var statements, and $\mathrm{xi} \ldots \mathrm{xj}$ are the (not necessarily contiguous) subset of $\mathrm{x} 1 \ldots \mathrm{xk}$ that are declared as uninitialized.

```
\(\operatorname{TrStmt}[[\operatorname{var} \mathrm{M} 1 \ldots \mathrm{Mn} \mathrm{x}, \mathrm{V}]]==\)
```

    skip
    $\operatorname{TrStmt}[[\operatorname{var} \mathrm{M} 1 \ldots \mathrm{Mn} \mathrm{x}=\mathrm{E}, \mathrm{V}]]==$
\#if (x declared with uninitialized)
Assign [[ x, E, V ]]
\#else
$\operatorname{Eval}[[\mathrm{x}=\mathrm{E}, \mathrm{V}]]$
\#end
where
$\operatorname{Assign}[[\mathrm{x}, \mathrm{E}, \mathrm{V}]]==$

```
#var e in
    TrExpr[[ E, {}, V, e ]];
    x=e ;
    #end
and where
Eval[[ E, V ]] ==
    #var junk in
    TrExpr[[ E, {}, V, junk ]]
#end
Note that, if x is declared as uninitialized, then Eval \([[\mathrm{x}=\mathrm{E}, \mathrm{V}]]\) sets init\$ x to true, whereas \(\operatorname{Assign}[[\mathrm{x}, \mathrm{E}\), V ]] does not assign to init\$x (except perhaps as a side effect of evaluating \(E\) ).
\(\operatorname{TrStmt}[[\) label L S, V ] \(]=\)
block L: \(\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]]\) end
\(\operatorname{TrStmt}[[\) skip, V\(]]==\)
skip
\(\operatorname{Tr} \operatorname{Stmt}[[\) eval E, V ]] ==
\(\operatorname{Eval[[E,~V]]}\)
\(\operatorname{TrStmt}[[\) if (E) S0 else S1, V ]] ==
\#var ein
\(\operatorname{Tr} \operatorname{Expr}[[\mathrm{E},\{ \}, \mathrm{V}, \mathrm{e}]]\);
if e then \(\operatorname{TrStmt}[[\mathrm{SO}]]\) else \(\operatorname{TrStmt}[[\mathrm{S} 1]]\) end
\#end
\(\operatorname{TrStmt}[[\) break L, V ]] == \(E C=\mathrm{L}\); raise
\(\operatorname{TrStmt}[[\) continue L, V ]] \(==\)
\(E C=\) continue \(\$ \mathrm{~L}\); raise
\(\operatorname{TrStmt}[[\) return, V\(]]==\)
\(E C=e c \$\) return ; raise
\(\operatorname{TrStmt}[[\) return E, V ] \(]=\)
Assign[[ RES, E, V ]];
\(E C=e c \$\) return ; raise
\(\operatorname{TrStmt}[[\) throw E, V ]] \(==\)
Assign \([[\) XRES, E ]];
check NullPointerException : XRES != null ;
\(E C=e c \$\) throw ; raise
We perform the \(X R E S!=\) null check here, and so does Sun's Java implementation, but it is not documented in either \(J L S\) or the Java bytecode specification.
Although Sun's Java implementation turns throwing null into a NullPointerException, we could actually give this error a different name that would better describe the error.
\(\operatorname{TrStmt}[[\operatorname{try} \mathrm{S}\) catch \((\mathrm{T} 1 \times 1 \mathrm{~S} 1)(\mathrm{T} 2 \times 2 \mathrm{~S} 2) \ldots(\mathrm{Tn} \times \mathrm{Sn} \mathrm{Sn})\) end, V\(]]==\)
\(\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]]!\)
if \(E C!=\) ec \(\$\) throw then skip else
if typeof \((\mathrm{X} R E S)<: \mathrm{T} 1\) then var x 1 in assume \(\mathrm{x} 1==\mathrm{X} R E S ; \operatorname{TrStmt}[[\mathrm{S} 1, \mathrm{~V}]]\) end else if typeof \((\mathrm{XRES})<: \mathrm{T} 2\) then var x 2 in assume \(\mathrm{x} 2=\mathrm{X} R E S ; \operatorname{TrStmt}[[\mathrm{S} 2, \mathrm{~V}]]\) end else
if typeof \((\mathrm{XRES})<:\) Tn then var xn in assume \(\mathrm{xn}==\mathrm{XRES} ; \operatorname{TrStmt}[[\mathrm{Sn}, \mathrm{V}]]\) end else
```

```
                raise
            end
        end
    end
end
TrStmt[[ try S0 finally S1, V ]] ==
    #var C0, C1 in
        #C0 = TrStmt[[ SO, V ]];
        #V = V ec res xres;
        #C1 = TrStmt[[ S1,V ]];
        (C0!
            assume ec== EC && res== RES && xres == XRES ;
            C1;
            EC=ec;RES=res;XRES=xres; raise
    ); C1
    #end
TrStmt[[ L: switch (E) (case [E1] S11 ... S1n 1) ... (case [Ek] Sk1 ... Sknnk) end, V ]] ==
    var x1 ... xk init$xi ... init$xj in
        #V = V e;
    Assign[[ e, E, V ]];
    block L:
        (( ( ( ...)( ( assume C1
                        ; TrStmt[[ S11, V ]] ; ...; TrStmt[[ S1n 1, V]]
                        )
                        [] assume C2
                                )
                                ; TrStmt[[ S21, V ]] ; .. ; TrStmt[[ S2n2, V ]]
                )
            [] assume C(k-1)
            )
            ; TrStmt[[ S(k-1)1, V ]] ; ..; ;TrStmt[[ S(k-1)n}\mp@subsup{\textrm{n}}{\textrm{k}-1}{},\textrm{V}]
            )
        [] assume Ck
        )
        ; TrStmt[[ Sk1, V ]] ; .. ; TrStmt[[ Skn k, V ]]
    end
    end
```

where $x 1 \ldots x k$ are the variables introduced by those of the statements $\mathrm{S} 11 \ldots \mathrm{Skn}_{\mathrm{k}}$ that are Java var statements, $\mathrm{xi} \ldots \mathrm{xj}$ are the (not necessarily contiguous) subset of $\mathrm{x} 1 \ldots \mathrm{xk}$ that are declared as uninitialized, and Ci is $e==\operatorname{Tr} \operatorname{Spec} \operatorname{Expr}[[\mathrm{Ei}]]$ if Ei is mentioned, or
$e!=\operatorname{TrSpecExpr}[[\mathrm{E} 1]] \& \& \ldots \& \& e!=\operatorname{TrSpecExpr}[[\mathrm{E}(\mathrm{i}-1)]] \& \&$
$e!=\operatorname{TrSpecExpr}[[\mathrm{E}(\mathrm{i}+1)]] \& \& \ldots \& \& e!=\operatorname{TrSpec} E x p r[[\mathrm{Ek}]]$
if $E i$ is omitted.

This translation of the switch statement relies on the assumption that all the case labels Ei are constant expressions that evaluate to distinct values, just like the Java language specification requires [JLS, 14.9].
$\operatorname{TrStmt}[[$ synchronized (E) S, V ]] $==$ $\# \mathrm{~V}=\mathrm{V} m u$; Assign[[ mu, E, V ]] ;
check LockingOrderViolation : mutex\$atmost( $\max (L S), m u) \| L S[m u]$;
We could introduce an annotation or command-line switch to drop the second disjunct, thus disallowing reentrant locking.
TrSynchronizedBody[[ mu, S, V ]]
where

```
TrSynchronizedBody[[ mu, S, V ]] ==
    \#V = V newLS;
assume (mutex\$atmost \((\max (L S), \mathrm{mu}) \& \& \mathrm{mu}==\max (\) newLS \()) \|\)
                        ( \(L S[\mathrm{mu}] \& \&\) new \(L S==L S\) );
assume newLS \(==\operatorname{store}(L S\), mu, bool\$true) ;
assume \(n e w L S==\operatorname{asLockSet}(n e w L S)\);
( \(\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]])[L S \quad\) newLS]
```

An alternative translation of the synchronized statement would be:
$\operatorname{TrStmt}[[$ synchronized (E) S, V ]] $==$
$\ldots$ as before until after the assume command ...
$\# \mathrm{~V}=\mathrm{V}$ old $L S$;
assume old $L S=L S$;
$L S=n e w L S$;
$\operatorname{TrStmt}[[$ try S finally $L S=o l d L S, \mathrm{~V}]]$

However, with this alternative translation, there is a risk that the prover will need to do a case analysis on normal versus exceptional termination of $S$ in order to establish that the value of $L S$ is the same after the synchronized statement as before.

The substitution in the actual translation can alternatively be implemented by passing a locking set variable name as a new parameter of TrStmt and of TrExpr, emitting this new parameter where the translation now emits $L S$. As another alternative, the current locking set name could be kept in a global variable.
$\operatorname{Tr}$ ConstructorCallStmt $[[$ construct $\mathrm{m}(\mathrm{E} 1 \mathrm{E} 2 \ldots \mathrm{En}), \mathrm{T}, \mathrm{V}]]==$
\#var e1 ... en in
$\operatorname{Tr} \operatorname{Expr}[[\mathrm{E} 1,\{\mathrm{E} 2 \ldots \mathrm{En}\}, \mathrm{V}, \mathrm{e} 1]] ; \ldots ; \operatorname{Tr} \operatorname{Expr}[[\mathrm{En},\{ \}, \mathrm{V}, \mathrm{en}]] ;$
call m(e1 ... en) ;
this $=$ RES
\#end
This is the only place where this is assigned.
$\operatorname{TrStmt}[[$ assert SE, V ] $]=$
check AssertionViolation : TrSpecExpr[[ SE ]]
$\operatorname{TrStmt}[[$ assume SE, V ]] ==
assume $\operatorname{TrSpecExpr}[[$ SE ]]
$\operatorname{TrStmt}[[$ unreachable, V$]]==$
check ReachabilityViolation : false

### 6.0 Translating loops

This section defines TrStmt on loops in terms of a function MakeLoop, which is also defined in this section.

```
\(\operatorname{TrStmt}[[\mathrm{L}\) : while (G) \{ loop_invariant J1 ... Jn \} S, V ]] ==
    \(\#\) var \(\mathrm{W}=\{ \}, \mathrm{CG}=\operatorname{Guard}[[\mathrm{G}, \mathrm{W}]], \mathrm{CS}=\operatorname{TrStmt}[[\mathrm{S}, \mathrm{W}]]\) in
    MakeLoop[[ var W in CG; block continue\$L: CS end end, J1 ... Jn, L, V ]]
    \#end
\(\operatorname{TrStmt}[[\mathrm{L}\) : do \{ loop_invariant \(\mathrm{J} 1 \ldots \mathrm{Jn}\} \mathrm{S}\) while (G), V ]] ==
    \(\# \boldsymbol{v a r} \mathrm{~W}=\{ \}, \mathrm{CS}=\overline{\operatorname{Tr}} \operatorname{Stmt}[[\mathrm{S}, \mathrm{W}]], \mathrm{CG}=\operatorname{Guard}[[\mathrm{G}, \mathrm{W}]]\) in
    MakeLoop [[ var W in block continue\$L: CS end ; CG end, J1 ... Jn, L, V ]]
    \#end
\(\operatorname{TrStmt}[[\mathrm{L}:\) for \((\operatorname{var} \mathrm{M} 1 \ldots \mathrm{Mn} \times[=\mathrm{E}] ; \mathrm{G} ; \mathrm{E} 1 \ldots \mathrm{En})\{\) loop_invariant \(\mathrm{J} 1 \ldots \mathrm{Jn}\} \mathrm{S}, \mathrm{V}]]==\)
        Out of curiosity, does our annotation language allow one of x 's modifiers to be uninitialized?
    \(\# \operatorname{var} \mathrm{~W}=\{ \}, \mathrm{CG}=\operatorname{Guard}[[\mathrm{G}, \mathrm{W}]], \mathrm{CS}=\operatorname{TrStmt}[[\mathrm{S}, \mathrm{W}]]\),
            \(\mathrm{CE}=(\operatorname{Eval}[[\mathrm{E} 1, \mathrm{~W}]] ; \ldots ; \operatorname{Eval}[[\mathrm{En}, \mathrm{W}]])\) in
```

```
    var x in
    TrStmt[[ var M1 ... Mn x [= E], V ]];
    MakeLoop[[ var W in CG ; block continue$L : CS end ; CE end, J1 ... Jn, L, V ]]
    end
#end
TrStmt[[ L: for (F1 ... Fk ; G ; E1 ... En) { loop_invariant J1 ... Jn } S, V ]] ==
    #var W = {}, CG = Guard[[ G, W ]], CS = TrStmt[[ S, W ]],
            CE = (Eval[[ E1,W ]] ; .. ; Eval[[ En, W ]] ) in
    Eval[[ F1, V ]] ; .. ; Eval[[ Fk, V ]];
    MakeLoop[[ var W in CG ; block continue$L : CS end ; CE end, J1 ... Jn, L, V ]]
#end
```

We now define MakeLoop. For any guarded command Body, two-state specification expressions J1 ... Jn denoting invariants, label L , and any V ,

```
MakeLoop[[ Body, J1 ... Jn, L, V ]] ==
    #var LoopTargs = NTargets[[ Body, {} ]], wt = MakeSubst[[ LoopTargs, L ]] in
    block L:
        var wt[[ LoopTargs ]] in
            #for w in LoopTargs do
                assume wt[[ w ]] == w ;
        Should this be an assumption or an assignment? The choice may have performance implications.
            #end
            loop
                { inv LoopInvariantViolation:TrSpecExpr[[ J1, {}, wt ]]
                    LoopInvariantViolation: TrSpecExpr[[ Jn, {}, wt ]]
                    LoopObjectInvariants[[ LoopTargs ]] }
                #for w in LoopTargs do
                    TargetTypeCorrect[[ w, wt ]] ;
                #end
                Body
            end
        end
    end
    #end
```

        If we use DesugarLoopFast (section 2.1), then the commands generated by the calls to TargetTypeCorrect (all of which are
        assume commands) are redundant and can be omitted.
        It may sometimes be desirable to leave out the loop invariants generated by the call to LoopObjectInvariants. This could be
        under the control of an ESC/Java command-line switch, but we conjecture that most ESC/Java users would want to omit the call
        to LoopObjectInvariants precisely when DesugarLoopFast (section 2.1) is used.
    where, for any list of variables v1 ... vm and location L, MakeSubst is defined as follows:

```
MakeSubst[[ v1 ... vm, L ]] ==
    {v1 v1@L,..., vm vm@L}
        MakeSubst allocates the AST nodes for the adorned names
```

and where, for any list of variables LoopTargs, LoopObjectInvariants is defined as follows:
LoopObjectInvariants[[ LoopTargs ]] ==
\#for every static invariant $J$ in scope, whose free variables intersect with LoopTargs ObjectInvariantViolationForLoop : TrSpecExpr[[ J ]]
\#end
\#for every object invariant J in scope, whose free variables intersect with LoopTargs ObjectInvariantViolationForLoop: (ALL this :: this != null ==> TrSpecExpr[[ J ]] ) \#end
and where, for any Java expression G, Guard is defined as follows:

```
\(\operatorname{Guard}[[\mathrm{G}, \mathrm{V}]]==\)
    \#var \(g\) in
        \(\operatorname{Tr} \operatorname{Expr}[[\mathrm{G},\{ \}, \mathrm{V}, \mathrm{g}]]\);
    if \(g\) then skip else raise \(L\) end
    \#end
```

and where, for any variable $\mathbf{w}$ and variable map wt, TargetTypeCorrect is defined as follows:

```
TargetTypeCorrect[[ w, wt ]] ==
    #if (w is a local variable or static field)
        assume TypeCorrect[[ w ]]
    #elsif (w is an instance variable)
        assume FieldTypeCorrect[[ w ]] ;
    #elsif (w is elems)
    assume ElemsTypeCorrect[[ w ]] ;
    #elsif (w is alloc)
    assume wt[[ alloc ]] < alloc;
    #elsif (w is an init$ variable)
    assume wt[[ w ]] ==> w
    #end
TypeCorrect[[ v ]] ==
    #let T be the declared type of v in
        #if (v is declared with non_null)
        TypeAndNonnullCorrectAs[[ v, T, true ]]
    #else
        TypeAndNonnullCorrectAs[[ v, T, false ]]
    #end
    #end
FieldTypeCorrect[[ f ]] ==
    #let T be the declared type of f in
        f== asField(f,T)
        #if (T is a reference type)
            && fClosedTime(f) < alloc
            #if (v is declared with non_null)
                && (ALL s :: allocTime(\overline{s})<\mathrm{ alloc }==>\textrm{f}[s]!= null)
            Do we need the antecedent?
            We have intentionally omitted the conjuncts s!= null && is(s,T) from the antecedent, because we think they are not needed.
            We had better check that we haven't done some other simplification elsewhere that would require f[null ] == null.
            #end
        #end
    #end
ElemsTypeCorrect[[ e ]] ==
    e==asElems(e)&& eClosedTime(e) < alloc
```


## 7 Synthesizing method specifications

In this section, we explain how to synthesize a method specification from an annotated Java method declaration and a scope. In particular, for a method m, a scope Sc, and list of variables SynTargs (called syntactic targets), we define two functions GetSpecForCall[[ m, Sc ]] and GetSpecForBody $[[\mathrm{m}, \mathrm{Sc}$, SynTargs ]], each of which returns a method specification of the form described in section 2.1:

```
spec T m(p1 ...pn) throws {X1 ... Xx}
precondition P1 ... precondition Pj
targets D1 ... Dk
```

```
whole-targets wt
postcondition Q1 ... postcondition Qm
```

The two functions are defined as follows:

```
GetSpecForCall[ \([\mathrm{m}, \mathrm{Sc}]]==\)
    ExtendSpecForCall[[ GetCommonSpec[[ m, Sc ]], Sc ]]
GetSpecForBody [[ m, Sc, SynTargs ]] ==
    ExtendSpecForBody[[ GetCommonSpec[[ m, Sc ]], Sc, SynTargs ]]
```

SynTargs will in fact always be the syntactic targets of the body of the method, see section 8.1.
The fact that ExtendSpecForBody takes a list of syntactic targets as a parameter may seem a little odd: Is the meaning of the method specification influenced by the implementation of the method? The reason for this parameter is so that ExtendSpecForBody can reduce the number of checked postconditions it adds, by suppressing those that are tautologies in the light of the body.

GetCommonSpec[[ m, Sc ]] ==
TrMethodDecl[[ FilterMethodDecl[[ GetCombinedMethodDecl[[ m ]], Sc ]] ]]
where GetCombinedMethodDecl, FilterMethodDecl, TrMethodDecl, ExtendSpecForCall, and ExtendSpecForBody are defined below.

The function GetCombinedMethodDecl combines the declaration of $m$ with the declarations of the methods that m overrides, producing a method declaration of the form:

```
method T m(p1 .. pn) throws {X1 .. Xx}
requires P1 \ldots. requires Pk
modifies w1 ... wu
ensures Q1 ... ensures Qh
```

In particular, GetCombinedMethodDecl is responsible for:

- Assembling the signature $\mathrm{Tm}(\mathrm{p} 1 \ldots \mathrm{pn})$ throws $\{\mathrm{X} 1 \ldots \mathrm{Xx}\}$. In the case of an instance method, this process includes prepending this to the list of declared parameters. In the case of a constructor, the return type $T$ is the class containing the constructor declaration. We assume that $m$ is represented in a form from which one can extract whether or not $m$ is a constructor, and that the declared parameters are represented in a form from which one can extract information such as type information and non_null information.
- Combining the requires pragmas of the method declaration of $m$ or of a method that $m$ overrides.
- Combining the modifies and also_modifies pragmas of the method declaration of $m$ and of the methods that m overrides.
- Combining the ensures and also_ensures pragmas of the method declaration of $m$ and of the methods that $m$ overrides.
- Replacing occurrences of the parameter names in the specifications combined from overridden methods with the corresponding parameter names of the overriding method.

Note that all expressions in the requires, modifies, and ensures clauses of the declaration returned by GetCombinedMethodDecl are specification expressions, not guarded command expressions.

Function FilterMethodDecl prunes away parts of the method declaration that mention variables that are not in scope. In particular, FilterMethodDecl is responsible for:

- Filtering the modifies list, removing designators that mention variables not in scope. This is unsound, but seems necessary in the absence of abstraction in the annotation language.
- Removing postconditions that mention variables not in scope. This is sound provided that the scope of each implementation gives rise to no pruning. The ESC/Java front end produces a syntactic warning if a programmer mentions a private variable in the specification of a non-private, non-final method (or override) in a non-final class. All other cases are sound.

Note that non-public classes mentioned as types of parameters, or as exceptions in the throws set, of a public method are not filtered out, despite the fact that a public caller do not have access to these classes. Courtesy of Java, thank you.

Function TrMethodDecl translates a (combined) method declaration into a method specification (see section 2.1). Given a method declaration, TrMethodDecl is responsible for:

- Generating checked preconditions from non_null parameter annotations.
- Translating requires clauses into checked preconditions.
- Generating checked preconditions for synchronized methods.
- Translating the modifies clause into a list of target designators, and adding alloc to this list. (This translation includes changing the specification designator E.g into just g, when g is a static field. Note that in the annotated Java AST, the name $g$ has already been disambiguated, so $E$ is not needed for the disambiguation).
In the presence of data groups, TrMethodDecl would be a nice place to compute downward closures.
- Computing a whole-targets map from the target designators.
- Translating ensures clauses into checked postconditions.
- Generating free preconditions from the types of the parameters, stating the type correctness of the parameters.
- Generating a free postcondition from the result type, stating the type correctness of the result.
- Generating a checked postcondition from the throws set, stating which exceptions, if any, are acceptable outcomes of the method.
- Generating a free postcondition from the throws set, stating the type correctness of any thrown exception.
- Generating free postconditions from the whole targets, stating their type correctness.
- Generating free postconditions from non_null annotations of the whole targets.

ExtendSpecForCall and ExtendSpecForBody extend what TrMethodDecl produces to take into account object invariants. This is done differently for callers and callees, so there are two functions. Function ExtendSpecForCall is responsible for:

- Generating checked preconditions from heuristically chosen object invariants and static invariants.
- Generating postconditions from the whole targets and from the object invariants and static invariants in scope, stating that the call does not invalidate any of the invariants.
and function ExtendSpecForBody is responsible for:
- Generating preconditions from the object invariants and static invariants in scope.
- Generating checked postconditions from whole targets, syntactic targets, object invariants, and static invariants, stating that the invariants are maintained.


### 7.0 GetCombinedMethodDecI

This section describes, for a given method name $m$, the various components of the result of GetCombinedMethodDecl[[ m ]].

### 7.0.0 Signature

If $m$ is a static method declared with parameters $p 1 \ldots p n$ and result type $T$ (possibly void) and throws set $\{\mathrm{X} 1 \ldots \mathrm{Xx}\}$, or if m is a constructor of a class T with declared parameters $\mathrm{p} 1 \ldots \mathrm{pn}$ and throws set $\{\mathrm{X} 1 \ldots$ $X x\}$, then GetCombinedMethodDecl[[ m$]]$ returns the signature
$\mathrm{T} m(\mathrm{p} 1 \ldots \mathrm{pn})$ throws $\{\mathrm{X} 1 \ldots \mathrm{Xx}\}$
If m is an instance method declared with parameters $\mathrm{p} 1 \ldots \mathrm{pn}$ and result type T (possibly void) and throws set $\{\mathrm{X} 1 \ldots \mathrm{Xx}\}$, then GetCombinedMethodDecl[[ m ]] returns the signature

## T m(this $\mathrm{p} 1 \ldots \mathrm{pn})$ throws $\{\mathrm{X} 1 \ldots \mathrm{Xx}\}$

Note that the variables $\mathrm{p} 1 \ldots \mathrm{pn}$ in these cases above have been unique-ified by the parser, which creates a distinct AST node for each variable, field, or parameter declaration. In particular, the declared parameters of a method are distinct from the declared parameters of any method that it overrides, even if the same textual names are used.

We define the reference declaration of a method $m$ as follows: If $m$ is not an override, the reference declaration of $m$ is the declaration of $m$; if $m$ overrides a method $m^{\prime}$ in a superclass, the reference declaration of $m$ is the reference declaration of $m^{\prime}$. The reference declaration of a constructor is the constructor itself; constructors cannot be overridden, since the constructor name declared must be the name of the class in which it occurs [ $J L S, 8.6$ ].

In the signatures described above, a parameter is considered to be declared non_null if the reference declaration of $m$ declared the corresponding parameter as non_null. Since the $\bar{E} S C / J a v a$ annotation language allows the non_null pragma to be used only for the parameters of reference declarations, the only way a parameter of an overriding method can be non_null is by inheritance of the non_null attribute as just described.

For generating location information in verification conditions, we need a mechanism by which given a parameter, one can extract the location of any inherited non_null pragma.

For use in the rest of this section, we now define a function that returns a substitution map to the parameter names of a method $m$ from the parameter names of the methods that $m$ overrides. For any method or constructor m :

```
ParameterMappings[[ m ]] ==
    #if (m}\mathrm{ is a reference declaration)
        {}
    #elsif (m directly overrides a method m')
        #let p1 ... pn be the declared parameters of m in
        ParmeterMappingsAux[[ m', p1 ... pn ]]
        #end
    #end
```

where

```
ParmeterMappingsAux[[ m, p1 ...pn ]] ==
    #let q1 ... qn be the declared parameters of m in
        #if (m is a reference declaration)
            {q1 p1,\ldots,qn pn}
    #elsif (m directly overrides a method m')
        {q1 p1,\ldots,qn pn}\cupParmeterMappingsAux[[ m', p1 .. pn ]]
        #end
    #end
```

In the rest of this section, let pmap denote ParameterMappings [[ m$]]$.

### 7.0.1 Combining requires clauses

Suppose the reference declaration of $m$ is declared with the requires pragmas:
requires P 1

## requires Pk

We should state the restriction that all variables mentioned in a requires pragma must be as visible as the method it specifies. Furthermore, if m is a constructor, then its requires pragmas are not allowed to mention this, either implicitly or explicitly.

Then, GetCombinedMethodDecl[[ m ]] includes the following requires clause:
requires pmap[[P1 ]]
requires pmap[[ Pk ]]

### 7.0.2 Combining modifies lists

Suppose

```
modifies \(\mathrm{w} 1 \ldots \mathrm{w}\)..
    modifies W.. ... W..
    also_modifies w.. ... w..
    also_modifies w.. ... wu
```

are the modifies and also_modifies pragmas of m and the methods it transitively overrides. (Note that a constructor is never annotated with an also_modifies pragma, because a constructor cannot be overridden.) GetCombinedMethodDecl[[ m ]] then includes
modifies pmap[[ w1 ]] ... pmap[[ wu ]]

### 7.0.3 Combining ensures clauses

Suppose

```
ensures Q1
ensures Q..
also_ensures Q..
also_ensures Qh
```

are the ensures and also_ensures pragmas of $m$ and the methods it transitively overrides. (Note that a constructor is never annotated with an also_ensures pragma, because a constructor cannot be overridden.) GetCombinedMethodDecl[ $[\mathrm{m}]]$ then includes

```
ensures pmap[[ Q1 ]]
```

ensures pmap[[ Qh ]]

### 7.1 FilterMethodDecl

Given a method declaration decl of the form
method T m(p1 ... pn) throws $\{\mathrm{X} 1 \ldots \mathrm{Xx}$ \}
requires $\mathrm{P} 1 \ldots$ requires Pk
modifies w1 ... wu
ensures Q1 ... ensures Qh
and a scope Sc , we define:

```
FilterMethodDecl[[ decl, Sc ]] ==
    method T m(p1 ... pn) throws {X1 ... Xx}
    requires P1 ... requires Pk
    modifies
#for w in w1 ... wu do
    #ff (all variables in w are visible in Sc)
            w
    #end
```

```
#end
#for Q in Q1 ... Qh do
    #if (all variables in Q are visible in Sc)
            ensures Q
    #end
#end
```

Note that for a static field g, a specification expression E.g would always evaluate to the same value as g. Function FilterMethodDecl, as defined here, filters out specification designators and postconditions containing expressions of the form E.g whenever $E$ contains some variable not in scope, even if $g$ is a static field that is in scope. An alternative design would be to transform E.g to g before filtering. In the current design, the translation of E.g into g occurs in TrMethodDecl.

### 7.2 TrMethodDecl

This section describes the various components of the result of TrMethodDecl for a given method declaration

```
method T m(p1 .. pn) throws {X1 .. Xx}
requires P1 _. requires Pk
modifies w1 ... wu
ensures Q1 ... ensures Qh
```

The signature returned by TrMethodDecl is the same as the one given.

### 7.2.0 Preconditions

We now describe the list of precondition clauses that the TrMethodDecl function returns.
TrMethodDecl[[ m ]] includes
\#for p in p1 ... pn do \#if ( p is this)
\#let $U$ be the class that declares $m$ in
precondition Free : is (this, U) \&\& allocTime (this) < alloc
precondition NullPointerException : this != null \#end
\#else
\#let $U$ be the type of $p$ in
precondition Free : is $(\mathrm{p}, \mathrm{U})$ \#if ( U is a reference type)
precondition Free : allocTime $(\mathrm{p})$ < alloc
\#if ( p is declared as non_null)
Recall that $p$ is considered to be declared as non_null if the corresponding parameter in the reference declaration of $m$ is declared as non_null.
precondition NonNullViolation: p != null
\#end
\#end
\#end
\#end
\#end
TrMethodDecl[[ m ]] also includes
precondition PreconditionViolation : TrSpecExpr[[ P1 ]]
precondition PreconditionViolation : TrSpecExpr[[ Ph ]]
Finally, if $m$ is a synchronized instance method, then $\operatorname{TrMethodDecl[[~} \mathrm{m}]]$ includes
precondition LockingOrderViolation : mutex\$atmost(max(LS), this) || LS[this]

We could introduce an annotation or command-line switch to drop the second disjunct, thus disallowing reentrant locking. For now, to forbid reentrancy into a synchronized method, the programmer must supply an explicit requires clause.
and if m is a synchronized static method of a class U , then $\operatorname{TrMethodDecl[[m]]~includes~}$
precondition LockingOrderViolation : mutex\$atmost(max(LS), U) \|LS[U]
In the second case, U is the class object [JLS, 17.13 and 20.3].
Currently, the annotation language does not let a user mention U as an argument to $<,<=$, or $L S[$ ], so there is no way to discharge proof obligations relating to the position of class objects in the locking order.

### 7.2.1 Targets

We now describe the targets and whole-targets clauses that the TrMethodDecl function returns.
TrMethodDecl[[ m ]] includes
targets BasicTargets[[ w1 ... wu ]]
where function BasicTargets is defined as:

```
BasicTargets[[ w1 ... wu ]] ==
    TrSpecExpr[[ w1 ]] ... TrSpecExpr[[ wu ]] alloc
```

Corresponding to the designator targets, $\operatorname{TrMethodDecl[[~m~]]~also~includes~the~following~whole~targets~}$ map:
whole-targets MakeSubst[[ ShaveAll[[ BasicTargets[[ w1 ... wu ]] ]], pre ]]
We assume that MakeSubst creates AST nodes for the new names.
where ShaveAll is defined to be a duplicate-free list of variable names, as follows:

```
ShaveAll[[ D1 ... Dd ]] ==
    #for D in D1 ... Dd do
    Shave[[ D ]]
    #end
```

but with duplicates removed, and Shave is defined as follows: for any variable v and expressions E0 and E1,

- Shave $[[\mathrm{v}]]==\mathrm{v}$
- Shave $[[\mathrm{v}[\mathrm{E} 0]]]==\mathrm{v}$
- Shave $[[\mathrm{v}[\mathrm{E} 0][\mathrm{E} 1]]]==\mathrm{v}$


### 7.2.2 Postconditions

We now describe the list of postcondition clauses that the TrMethodDecl function returns. Throughout this section, we let wt denote the map created for the whole-targets clause as described above.

Every method and constructor body is allowed to allocate new objects, and hence may advance the current allocation time. Thus, TrMethodDecl[[ m ]] includes
postcondition Free: wt[[ alloc ]] < alloc
Note that if our translation were to assume free postconditions at the end of a body, as a possible aid in discharging the checked postconditions, the free postcondition described here may provide more aid than warranted. The problem is that the body might do no allocations, in which case $w t[[$ alloc $]]==$ alloc at the end of the body. Were this to become an issue, we could change the $<$ in this free postcondition to an $<=$. For now, we're leaving it as $<$, because we currently don't assume free postconditions at the end of the body and we don't know if using <= would give rise to case splits in reasoning about calls.

This postcondition is free, because the programming language offers no way to decrease the allocation time.

If $m$ is a constructor, then $\operatorname{TrMethodDecl[[m]]~includes~}$
postcondition Free : RES != null \&\& wt[[ alloc ]] < allocTime(RES)
If T is not void, then $\operatorname{TrMethodDecl[[~} \mathrm{m}]]$ includes
postcondition Free : TypeCorrectAs[[ RES, T ]]
Note that no antecedent $E C=$ ec $\$$ return is needed, because only if the call returns normally does the caller actually use $R E S$.
TrMethodDecl[[ m ]] also includes
postcondition Free : $E C=e c \$$ throw $==>$
XRES $!=$ null \&\& typeof $(X R E S)<:$ Throwable \&\& allocTime $(X R E S)<$ alloc
postcondition UnexpectedException :
EC==ec\$return \|
$(E C=$ ec\$throw $\& \&($ typeof $(X R E S)<: \mathrm{X} 1\|\ldots\|$ typeof $(X R E S)<: \mathrm{Xx}))$
If the throws set is empty, then this checked postcondition simplifies to $E C=$ ec $\$$ return.
Finally, TrMethodDecl[[ m ]] includes

```
#for Q in Q1 .. Qh do
    postcondition PostconditionViolation: EC ==ec$return ==> TrSpecExpr[[ Q, {}, wt ]]
    If the throws set is empty, then the antecedent }EC== ec$return can be dropped
#end
```


### 7.3 ExtendSpecForCall

This section describes, for a given method specification spec of the form

```
spec T m(p1 ...pn) throws {X1 ... Xx}
precondition P1 ... precondition Pj
targets D1 ... Dk
whole-targets wt
postcondition Q1 ... postcondition Qm
```

and a scope Sc, the various components of the result of ExtendSpecForCall[[ spec, Sc ]]. Function ExtendSpecForCall returns a method specification like spec but extended with additional precondition and postcondition clauses. These conditions arise from heuristically chosen object invariants and static invariants.

### 7.3.0 Adding preconditions

We now describe the list of additional precondition clauses that ExtendSpecForCall returns.
We start with a couple of definitions. An invariant $J$ declared in a class $T$ is an object invariant of T if J mentions this, and is a static invariant of T otherwise. An invariant is called Sc-visible if it is in scope in Sc.

These definitions would be better placed elsewhere, perhaps near the (to be written) AST grammar of declarations.
For every static invariant $J$ in scope Sc , ExtendSpecForCall[[ spec, Sc ]] includes
precondition StaticInvariantViolation : TrSpecExpr[[ J ]]
For each static field $g$ in scope Sc, if the static type of $g$ is a class U, then ExtendSpecForCall[[ spec, Sc ]] includes
precondition ObjectInvariantViolation: $\mathrm{g}==$ null $\| \operatorname{TrSpecExpr}\left[\left[\begin{array}{ll}\mathrm{J},\{\text { this } & \mathrm{g}\},\{ \}]]\end{array}\right.\right.$
The first disjunct can be suppressed if $g$ is declared as non_null.
for every Sc -visible object invariant J of any superclass of U .
For each parameter $p$ in the signature of spec, if the static type of $p$ is a class $U$ (or if $p$ is this and $m$ is a method of a class U), then ExtendSpecForCall[[ spec, Sc ]] includes
precondition ObjectInvariantViolation : $\mathrm{p}==$ null $\| \operatorname{TrSpecExpr}\left[\left[\begin{array}{lll}\left.\left.\mathrm{J},\left\{\begin{array}{ll}\text { this } & \mathrm{p}\end{array}\right\},\{ \}\right]\right]\end{array}\right.\right.$
The first disjunct can be suppressed if p is this or is declared as non_null.
for every Sc -visible object invariant J of any superclass of $U$.

### 7.3.1 Adding postconditions

We now describe the list of additional postcondition clauses that ExtendSpecForCall returns.
The postconditions generated here are used only in the desugaring of calls. In this context, the predicates of all postconditions are assumed and the error names are ignored. Since the error names are ignored, we have written them as Free.

For every Sc-visible static invariant J, ExtendSpecForCall[[ spec, Sc ]] includes

```
postcondition Free : TrSpecExpr[[ J ]]
```

As an important optimization, this postcondition clause is suppressed for $J$ if the free variables of $J$ are disjoint from the domain of wt (in which case this postcondition is a tautology).

For every Sc-visible object invariant J of any class U, ExtendSpecForCall[[ spec, Sc ]] includes
\#if ( $m$ is a constructor, and $U$ is a proper subtype of $T$ )

$$
\text { postcondition Free : (ALL } s:: \text { TypeCorrectAs }[[s, \cup]] \& \& s!=\text { null \&\& } s!=\text { this \&\& }
$$

$$
\left.\left.\left.\left.\begin{array}{l}
\text { TrSpecExpr }[[\mathrm{J},\{\text { this } \quad s\} \cup \mathrm{wt},\{ \}]] \\
==\operatorname{TrSpecExpr}[[\mathrm{J},\{\text { this } \\
s
\end{array}\right\},\{ \}\right]\right]\right) .
$$

\#else

$$
\begin{aligned}
\text { postcondition Free : (ALL } s:: & \text { TypeCorrectAs }[[\mathrm{s}, \mathrm{U}]] \& \& s!=\text { null \&\& } \\
& \operatorname{TrSpecExpr}[[\mathrm{J},\{\text { this } s\} \cup \mathrm{wt},\{ \}]] \\
& ==\operatorname{TrSpecExpr}[[\mathrm{J},\{\text { this } s\},\{ \}]])
\end{aligned}
$$

\#end
where $s$ is a fresh name. As an important optimization, this postcondition clause is suppressed for J if the free variables of $J$ are disjoint from the domain of $w t$.

What should be the trigger for these quantifications?

### 7.4 ExtendSpecForBody

This section describes, for a given call specification spec of the form

```
spec T m(p1 ...pn) throws {X1 ... Xx}
precondition P1 ... precondition Pj
targets D1 ... Dk
whole-targets wt
postcondition Q1 ... postcondition Qm
```

and a scope Sc and a list of variables (syntactic targets) SynTargs, the various components of the result of ExtendSpecForBody[[ spec, Sc, SynTargs ]]. Function ExtendSpecForBody returns a method specification like spec but extended with additional postcondition clauses. These postconditions arise from object invariants and static invariants.

### 7.4.0 Adding preconditions

The specification returned by ExtendSpecForBody includes the following precondition clauses in addition to the precondition clauses in spec.

The preconditions generated here are used only in generating the verification for a body. In this context, the predicates of all preconditions are assumed and the error names are ignored. Since the error names are ignored, we have written them as Free.

For every Sc-visible static invariant J, ExtendSpecForBody[[ spec, Sc, SynTargs ]] includes
precondition Free: TrSpecExpr[[ J ]]
For every Sc-visible object invariant J of any class U, ExtendSpecForBody[[ spec, Sc, SynTargs ]] includes
precondition Free: (ALL $s::$ TypeCorrectAs[[ $s$, U ]] \&\& $s$ != null
$\Rightarrow \operatorname{TrSpecExpr}[[\mathrm{J},\{$ this $s\},\{ \}]])$

### 7.4.1 Adding postconditions

The specification returned by ExtendSpecForBody includes the following postcondition clauses in addition to the postcondition clauses in spec.

For every Sc-visible static invariant J, ExtendSpecForBody[[ spec, Sc, SynTargs ]] includes

```
postcondition StaticInvariantViolation : TrSpecExpr[[ J ]]
```

As an important optimization, this postcondition clause is suppressed for $J$ if the free variables of $J$ are disjoint from SynTargs (in which case the condition follows immediately from the assumption, placed in the scope-specific background predicate, that all object invariants hold initially).

For every Sc-visible object invariant J of any class U, ExtendSpecForCall[[ spec, Sc, SynTargs ]] includes
\#if ( $m$ is a constructor, and $U$ is a proper subtype of $T$ )
postcondition ObjectInvariantViolation:
$\begin{aligned} \text { (ALL } s & :: \text { TypeCorrectAs }[[s, \mathrm{U}]] \& \& s!=\text { null } \& \& s!=\text { this } \\ & ==\operatorname{TrSpecExpr}[[\mathrm{J},\{\text { this } s\},\{ \}]])\end{aligned}$
\#else
postcondition ObjectInvariantViolation:
(ALL $s::$ TypeCorrectAs $[[s, \mathrm{U}]] \& \& s!=$ null \&\&
$==>\operatorname{TrSpecExpr}[[\mathrm{J},\{$ this $s\},\{ \}]])$
\#end
where $s$ is a fresh name. As an important optimization, this postcondition clause is suppressed for J if the free variables of $J$ are disjoint from SynTargs.

What should be the trigger for these quantifications?

## 8 Verification conditions

A verification condition consists of a set of background axioms (described in ESCJ 8, The logic of $E S C / J a v a$ ), a class-specific (that is, scope-specific) background predicate, and method-specific predicate.

### 8.0 Scope-specific background predicate

In this section, we define two functions, PreMap and InitialState.
Given a scope Sc, PreMap[[ Sc ]] returns a map from every field in Sc, and from elems and from alloc, to corresponding variables adorned with @pre.

As a side effect, PreMap creates AST nodes for these adorned variables.
$\operatorname{PreMap}[[$ Sc $]]==$
\#for every static field $g$ visible in Sc do
\{g g@pre\} $\cup$
\#end
\#for every instance variable $f$ visible in Sc do

```
    {f f@pre}\cup
#end
{elems elems@pre}\cup
{alloc alloc@pre}
```

The scope-specific background predicate is generated by the function InitialState[[ Sc, premap ]]. It is defined as follows, for any scope Sc and map from variables to variables premap,

```
InitialState[[ Sc, premap ]] ==
    \#for every static field \(g\) visible in Sc do
        premap \([[\mathrm{g}]]==\mathrm{g} \& \&\)
        TypeCorrect[[ g ]] \&\&
    \#end
    \#for every instance variable \(f\) of type \(T\) visible in Sc do
        premap[[ f ] ] == f \&\&
        FieldTypeCorrect[[ f ]] \&\&
    \#end
    premap \([[\) elems \(]]==\) elems \(\& \&\)
    ElemsTypeCorrect [[ elems ]] \&\&
\(L S==\operatorname{asLockSet}(L S) \& \&\)
    premap \([[\) alloc \(]]==\) alloc
```


### 8.1 Methods and constructors

This section describes the verification condition for a method or constructor $m$ with a Java body $S$ in scope Sc.

Let premap denote PreMap[[ Sc ]], let body denote $\operatorname{TrBody}[[\mathrm{m}, \mathrm{S}$, premap ]] (defined below), let SynTargs denote NTargets[[ body, $\}$ ]], and let spec denote the method specification

```
spec T m(p1 ...pn) throws {X1 ... Xx}
precondition P1 ... precondition Pj
targets D1 ... Dk
whole-targets wt
postcondition Q1 ... postcondition Qm
```

returned by GetSpecForBody[[ m, Sc, SynTargs ]]. Then, the verification condition for $m$ declared at location $L$ in scope Sc with body S is:

```
BackgroundAxioms[[ Sc ]] \&\&
InitialState[[ Sc, premap ]] \&\&
P1 \&\& ... \&\& Pj
-
\(e j p[[\) body ;
            check L, Q1 ; ... ; check L, Qm ;
            CheckModifiesConstraints[[ spec, Sc, SynTargs, premap ]]
            , true, true ]]
```

We now define TrBody and CheckModifiesConstraints.

Function TrBody translates the Java body S into a guarded command.

```
\(\operatorname{TrBody}[[\mathrm{m}, \mathrm{S}\), premap \(]]==\)
    \#var \(V=\{ \}, C S\) in
        \#if ( m is a method, not a constructor)
        \#if ( m is a synchronized instance method)
            \#CS \(=\) TrSynchronizedBody[[ this, S, V ]]
        \#elsif ( \(m\) is a synchronized static method of a class \(U\) )
            \#CS = TrSynchronizedBody [[ U, S, V ]]
        \#else
            \#CS \(=\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]]\)
        \#end
        Note that constructors cannot be synchronized [JLS, 8.6.3].
        \#elsif ( \(m\) is a constructor of a class T , and
                    \(S\) has the form construct \(m^{\prime}(\ldots) ; S^{\prime}\) (where \(S^{\prime}\) may be the empty statement) )
        \#if ( \(\mathrm{m}^{\prime}\) is a constructor of class T )
            // this is a call to a sibling constructor
            \#CS \(=\left(\operatorname{TrStmt}\left[\left[\right.\right.\right.\) construct \(\mathrm{m}^{\prime}(\mathrm{E} 1 \ldots\) En \(\left.\left.), \mathrm{V}\right]\right]\);
                    assume typeof(this) \(<\) : T ;
                            \(\operatorname{TrStmt}\left[\left[\mathrm{S}^{\prime}, \mathrm{V}\right]\right]\) )
        \#else
            // this is a call to a superclass constructor
            \#CS \(=\left(\operatorname{TrStmt}\left[\left[\right.\right.\right.\) construct \(\mathrm{m}^{\prime}(\mathrm{E} 1 \ldots\) En \(\left.\left.), \mathrm{V}\right]\right]\);
                    assume typeof(this) \(<\) : T ;
                        InstanceInitializers[[ T, V ]];
                            \(\operatorname{TrStmt}\left[\left[\mathrm{S}^{\prime}, \mathrm{V}\right]\right]\) )
        \#end
        \#else
        // this is a constructor of class Object that does not call any sibling constructor
        \#CS = ( modify this ; modify alloc ;
                        assume premap \([[\) alloc \(]]<\) alloc ;
                        assume premap \([[\) alloc \(]]<\) allocTime(this) \&\& allocTime(this) <alloc ;
                        assume this \(!=\) null \&\& typeof(this) <: Object ;
                        InstanceInitializers [[ Object, V ]];
                        \(\operatorname{TrStmt}[[\mathrm{S}, \mathrm{V}]])\)
        \#end
        var p1@pre ... pn@pre in
        Note, the parameters p1 ... pn are not in the domain of premap. The AST nodes for these @pre variables are thus allocated
        here.
        p1@pre=p1; ... ; pn@pre=pn ;
        var V in
            ( \(\mathrm{CS} ; E C=\) ec\$return
            \#if ( m is a constructor)
                ; \(R E S=\) this
            \#end
        ) ! skip
        end;
        p1 = p1@pre ; ... ; pn = pn@pre
        end
\#end
where for any class type T,
InstanceInitializers \([[\mathrm{T}, \mathrm{V}]]==\)
\#for every instance variable \(f\) of type \(U\) declared in class \(T\) in order do \#if ( T is boolean)
assume \(\mathrm{f}[\) this \(]\) != bool\$true;
```

```
    #elsif (T is an integral type)
        assume f[this]== 0;
    #elsif (T is a reference type)
    assume f[this] == null;
    #elsif (T is a floating point type)
    assume f[this]== cast (0,T);
    #end
#end
#for every instance variable f with an initializer E declared in class T in order do
    #var e in
        TrExpr[[ E, {}, V, e ]];
        WriteCheck[[ f[this], e ]];
        f[this]= e
    #end
#end
```

Function CheckModifiesConstraints takes a list of designator targets, a whole-targets map, and a list of syntactic targets, and produces a sequence of check commands. These checks enforce that the body meets the modifies list of the specification. Let spec be a method specification of the form shown above. Then, for a scope Sc and a list of variables (syntactic targets) SynTargs:

```
CheckModifiesConstraints[[ spec, Sc, SynTargs, premap ]] ==
    #for every static field g in SynTargs and not in Domain[[ wt ]] do
            check ModifiesViolation: premap[[g ]] == g
#end
#for every instance variable f in SynTargs do
    #let U be the class that declares f in
            #let q1 \ldots. qs be the subset of p1 \ldots. pn whose types are subtypes of U in
            #let g1 ...gr be the static fields in Sc whose types are are subtypes U in
                    check ModifiesViolation:
                    (ALL s :: s != null && (s== q1 | .. | s== qs | s == g1 | ..| | s== gr)
                                    ==>
                                    premap[[ f ]] [s]== f[s]| IsModPoint[[s, f, D1 ... Dk]])
            #end
        #end
    #end
#end
#if (elems is in SynTargs)
    #let q1 ... qs be the subset of p1 ... pn whose types are array types in
        #let g1 ... gr be the static fields in Sc whose types are array types in
                check ModifiesViolation:
                            (ALL }a::a!= null && ( a== q1 | ..||a== qs |a== g1| ..||a== gr
                        ==>
                        (ALL i :: premap[[ elems ]] [a][i]== elems[a][i])|
                        IsArrayModPoint[[ a, D1 ... Dk ]] )
                check ModifiesViolation:
                    (ALL a,i::a!= null && ( }a==\textrm{q}1|\ldots|a== qs |a== g1| ..||a== gr)
                        premap[[ elems ]] [a][i]== elems[a][i]|IsIndexModPoint[[ a,i, D1 ... Dk ]] )
        Perhaps we also want to require modifications of p.arr[i], where p is a parameter, arr is a field of p, and i is some index into
        p.arr, to be explicitly mentioned in a modifies clause. If so, we should add some more disjuncts of the form a== p.arr.
        #end
    #end
#end
```

We now define IsModPoint, IsArrayModPoint, and IsIndexModPoint.

For any name s, instance variable name f , and specification designator list $\mathrm{D} 1 \ldots \mathrm{Dk}$, function IsModPoint produces a predicate stating that the modifies list D1 ... Dk allows $f$ to be modified at $s$ :

```
IsModPoint \([[\mathrm{s}, \mathrm{f}, \mathrm{D} 1 \ldots \mathrm{Dk}]]==\)
    \#if ( \(\mathrm{k}==0\) )
    false
    \#elsif (D1 has the form \(f[E]\) for some \(E\) )
        \(\mathrm{s}==\mathrm{E}| |\) IsModPoint [[ s, f, D2 ... Dk ]]
    \#else
        IsModPoint[[ s, f, D2 ... Dk ]]
    \#end
```

For any names a and i , and specification designator list $\mathrm{D} 1 \ldots \mathrm{Dk}$, function IsArrayModPoint produces a predicate stating that the modifies list D1 ... Dk allows elems to be modified at a, and function IsIndexModPoint produces a predicate stating that the modifies list D1 ... Dk allows elems[a] to be modified at i :

IsArrayModPoint[[ a, D1 ... Dk ]] == \#if $(k==0)$
false
\#elsif (D1 has the form elems[E0][E1] for some E0 and E1) ( $\mathrm{a}==\mathrm{E} 0$ ) || IsArrayModPoint[[ a, D2 ... Dk ]]
\#elsif (D1 has the form elems [E] for some E) $(\mathrm{a}==\mathrm{E}) \|$ IsArrayModPoint $[[\mathrm{a}, \mathrm{D} 2 \ldots \mathrm{Dk}]]$
\#else
IsArrayModPoint[[ a, D2 ... Dk ]]
\#end
IsIndexModPoint [[ a, i, D1 ... Dk ]] $==$
\#if ( $k==0$ )
false
\#elsif (D1 has the form elems[E0][E1] for some E0 and E1)
$(\mathrm{a}=\mathrm{E} 0$ \&\& $\mathrm{i}==\mathrm{E} 1) \|$ IsIndexModPoint $[[\mathrm{a}, \mathrm{i}, \mathrm{D} 2 \ldots \mathrm{Dk}]]$
\#elsif (D1 has the form elems [E] for some E)
( $\mathrm{a}==\mathrm{E}$ ) || IsIndexModPoint[[ a, i, D2 ... Dk ]]
\#else
IsIndexModPoint[[ a, i, D2 ... Dk ]]
\#end

### 8.2 Static bodies

TBW.


[^0]:    Are there other sources of unsoundness? It would useful to have a document describing all the sources of unsoundness and incompleteness in the ESC/Java checker, including those introduced by the Java-to-GC translator, the VC generator, and the prover.

[^1]:    The actual ESC/Java implementation simply uses booleans where we use sets of protect expressions. Where we have written a set $\{\mathrm{p} 1 \ldots \mathrm{pn}\}$ as a protect argument to $\operatorname{TrExpr}$, the implementation passes the boolean Impure $[[\mathrm{p} 1]]\|\ldots\|$ Impure $[$ [ pn ]], where Impure[[ pi ]] is defined as described above if pi is a Java expression and as true if pi has the form $\mathrm{F}=$. Since $\operatorname{TrExpr}$ usually passes its protect argument to Protect, the actual ESC/Java implementation uses a boolean for this parameter, too, and implements Protect as follows:

    ```
    Protect[[ e, p, V, r ]] ==
    #if (p && (e mentions any Java non-final local variable, non-final field, elems, or alloc))
    #V = V v;
    #r = v;
    v=e;
    #else
    #r=e;
    #end
    ```

